

Water Resources Systems: Modeling Techniques and Analysis

Lecture - 7 Course Instructor: Prof. P. P. MUJUMDAR Department of Civil Engg., IISc.

Summary of the previous lecture

- Function with equality constraints
 - Lagrange multipliers

$$L = f(X) - \sum_{j=1}^{m} \lambda_{j} g_{j}(X)$$

Necessary condition:

$$\frac{\partial L}{\partial x_i} = 0; \ \frac{\partial L}{\partial \lambda_j} = 0$$

Sufficiency condition: |D| = 0

• Function with inequality constraints Minimize *f*(*X*)

$$\left| \mathcal{D} \right| = \mathbf{0}$$
$$L_{ij} = \frac{\partial^2 L}{\partial x_i \partial x_j} \bigg|_{(X^*, \lambda^*)}; g_{ji} = \frac{\partial g_j(X)}{\partial x_i} \bigg|_{X^*}$$

s.t.

$$g_j(X) \le 0$$
 $j = 1, 2, ..., m$

Kuhn – Tucker conditions:
$$\frac{\partial f}{\partial x_i} + \sum_{j=1}^m \lambda_j \frac{\partial g_j}{\partial x_i} = 0 \quad i = 1, 2, \dots, n$$
$$\lambda_j g_j = 0$$
$$g_j \le 0 \quad j = 1, 2, \dots, m$$
$$\lambda_j \ge 0$$

Example – 1

Maximize

$$f(X) = -x_1^2 - x_2^2 + 4x_1 + 4x_2 - 8$$

s.t.

$$x_1 + 2x_2 \le 4$$
$$2x_1 + x_2 \le 5$$

K-T conditions $\frac{\partial f}{\partial x_{i}} + \sum_{j=1}^{2} \lambda_{j} \frac{\partial g_{j}}{\partial x_{i}} = 0$ i = 1, 2 $\lambda_{j}g_{j} = 0$ $g_{j} \leq 0$ $\lambda_{j} \leq 0$ j = 1, 2

Let $f(X) = -x_1^2 - x_2^2 + 4x_1 + 4x_2 - 8$ $g_1(X) = x_1 + 2x_2 - 4$ $g_2(X) = 2x_1 + x_2 - 5$

K-T conditions

$$\frac{\partial f}{\partial x_i} + \sum_{j=1}^2 \lambda_j \frac{\partial g_j}{\partial x_i} = 0 \qquad i = 1, 2$$

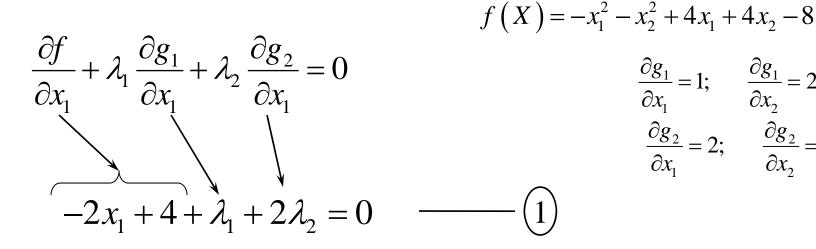
$$\frac{\partial f}{\partial x_i} + \lambda_1 \frac{\partial g_1}{\partial x_i} + \lambda_2 \frac{\partial g_2}{\partial x_i} = 0$$

4

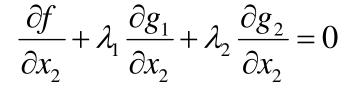
$$g_1(X) = x_1 + 2x_2 - 4$$
$$\frac{\partial g_1}{\partial x_1} = 1; \qquad \frac{\partial g_1}{\partial x_2} = 2$$

$$g_2(X) = 2x_1 + x_2 - 5$$

$$\frac{\partial g_2}{\partial x_1} = 2; \qquad \frac{\partial g_2}{\partial x_2} = 1$$



$$\frac{\partial g_1}{\partial x_1} = 1; \qquad \frac{\partial g_1}{\partial x_2} = 2$$
$$\frac{\partial g_2}{\partial x_1} = 2; \qquad \frac{\partial g_2}{\partial x_2} = 1$$



$$-2x_2 + 4 + 2\lambda_1 + \lambda_2 = 0 \quad ----(2)$$

$$\lambda_2 (2x_1 + x_2 - 5) = 0$$
 -----(4)

4 equations and 4 unknowns

Using Eq.1 and Eq.2

$$-2x_{1} + 4 + \lambda_{1} + 2\lambda_{2} = 0$$
$$-2x_{2} + 4 + 2\lambda_{1} + \lambda_{2} = 0$$

multiplying eq.1 with 2 and subtracting eq.2, rearranging the terms

$$2\lambda_{1} + 4\lambda_{2} = 4x_{1} - 8$$

$$2\lambda_{1} + \lambda_{2} = 2x_{2} - 4$$

$$3\lambda_{2} = 4x_{1} - 2x_{2} - 4; \qquad \lambda_{2} = \frac{4x_{1} - 2x_{2} - 4}{3}$$

Substituting in Eq.2,

$$\lambda_{1} = \frac{-2x_{1} + 4x_{2} - 4}{3} \qquad \qquad \lambda_{1}(x_{1} + 2x_{2} - 4) = 0$$
$$\lambda_{2}(2x_{1} + x_{2} - 5) = 0$$

Substituting λ_1 and λ_2 in Eq.3 and Eq.4,

$$(-2x_1 + 4x_2 - 4)(x_1 + 2x_2 - 4) = 0 - ----(5)$$

$$(4x_1 - 2x_2 - 4)(2x_1 + x_2 - 5) = 0 \quad ----6$$

Four solutions possible

First terms in both Eq.5 and Eq.6,

$$(-2x_1 + 4x_2 - 4) = 0$$

 $(4x_1 - 2x_2 - 4) = 0$

Solving the equations gives,

$$x_1 = 2; \qquad x_2 = 2$$

Check for conditions

$$g_j \le 0$$

$$\lambda_j \le 0$$

$$j = 1, 2$$

$$\lambda_{1} = \frac{-2x_{1} + 4x_{2} - 4}{3} = 0$$

$$\lambda_{2} = \frac{4x_{1} - 2x_{2} - 4}{3} = 0$$

 $\lambda_j \leq 0$ Condition is satisfied

$$g_1(X) = x_1 + 2x_2 - 4 = 2$$
$$g_2(X) = 2x_1 + x_2 - 5 = 1$$

 $g_j \le 0$ Condition is not satisfied

Check for other solutions

Second terms in both Eq.5 and Eq.6,

$$(x_1 + 2x_2 - 4) = 0$$

 $(4x_1 - 2x_2 - 4) = 0$

Solving the equations gives,

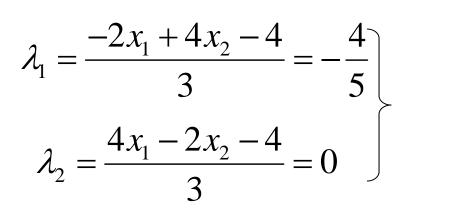
$$x_1 = \frac{8}{5}; \qquad x_2 = \frac{6}{5}$$

Check for conditions

$$g_{j} \leq 0$$

$$\lambda_{j} \leq 0$$

$$j = 1, 2$$



 $\lambda_j \leq 0$ Condition is satisfied

$$g_{1}(X) = x_{1} + 2x_{2} - 4 = 0$$

$$g_{j} \leq 0$$

$$g_{2}(X) = 2x_{1} + x_{2} - 5 = -\frac{3}{5}$$
Condition is satisfied
Therefore, $\left(\frac{8}{5}, \frac{6}{5}\right)$ satisfies all K-T conditions

First term in Eq.5 and second term in Eq.6,

$$(-2x_1 + 4x_2 - 4) = 0$$
$$(2x_1 + x_2 - 5) = 0$$

Solving the equations gives,

$$x_1 = \frac{8}{5}; \qquad x_2 = \frac{9}{5}$$

Check for conditions

$$g_j \le 0$$

$$\lambda_j \le 0$$

$$j = 1, 2$$

$$\lambda_{1} = \frac{-2x_{1} + 4x_{2} - 4}{3} = 0$$

$$\lambda_{2} = \frac{4x_{1} - 2x_{2} - 4}{3} = -\frac{2}{5}$$

 $\lambda_j \leq 0$ Condition is satisfied

$$g_1(X) = x_1 + 2x_2 - 4 = \frac{6}{5}$$
$$g_2(X) = 2x_1 + x_2 - 5 = 0$$

 $g_j \le 0$ Condition is not satisfied

Check for other solutions

Second term in Eq.5 and second term in Eq.6,

 $\left(x_1+2x_2-4\right)=0$

 $\left(2x_1+x_2-5\right)=0$

Solving the equations gives,

$$x_1 = 2; \quad x_2 = 1$$

Check for conditions

$$g_j \le 0$$

$$\lambda_j \le 0$$

$$j = 1, 2$$

$$\lambda_{1} = \frac{-2x_{1} + 4x_{2} - 4}{3} = -\frac{4}{3}$$
$$\lambda_{2} = \frac{4x_{1} - 2x_{2} - 4}{3} = \frac{2}{3}$$

 $\lambda_j \leq 0$

Condition is not satisfied

$$g_1(X) = x_1 + 2x_2 - 4 = 0$$
$$g_2(X) = 2x_1 + x_2 - 5 = 0$$

 $\begin{cases} g_j \le 0 \\ \\ \text{Condition is satisfied} \end{cases}$

Hence the optimal solution to the problem is

$$x_1^* = \frac{8}{5}; \qquad x_2^* = \frac{6}{5}$$

LINEAR PROGRAMMING

Linear Programming

- Linear programming (LP) is an optimization method applicable for solution of problems with objective function and constraints as a linear functions of decision variables.
- Linear equations may be in the form of equalities or inequalities.
- During World War II, George B. Dantzig formulated general LP problem for allocating resources, and devised the simplex method of solution.
- LP is considered as a revolutionary development that permits us to make optimal decisions in complex situations.

Source: "Engineering and optimization-theory and practice" by Singiresu S. Rao, 1996, John Wiley & Sons

Linear Programming

- Simplex method is most efficient and popular method.
- Karmakar's method is 50 times faster than simplex method – developed in 1984.
- Some applications of LP in water resources
 - Reservoir operation
 - Irrigation scheduling
 - Reservoir capacity determination
 - Screening of alternatives in river basin development.
 - Conjunctive use of surface and ground water
 - Resource allocation
- 25% of all problems solved in computers.

Linear Programming

General form of a LP

Linear objective function f(X) is linear function of X

linear constraints \dots g_i(X) are all linear functions of X

non-negativity of variables $X \ge 0$

LINEAR PROGRAMMING Graphical Solution

LP – Graphical Solution

- Graphical method gives a physical picture of certain geometrical characteristics of LP problem.
- Complex as the no. of variables increases.

Example – 2

Maximize

s.t.

$$Z = 3x_{1} + 5x_{2}$$

$$x_{1} \le 4$$

$$2x_{2} \le 12$$

$$3x_{1} + 2x_{2} \le 18$$
Constraints
$$x_{1} \ge 0$$

$$x_{1} \ge 0$$
Decision variables
$$x_{2} \ge 0$$
Decision variables
$$x_{1} = 0$$

$$x_{2} \ge 0$$

