

# Stochastic Structural Dynamics

## Lecture-7

### Random processes-2

Dr C S Manohar

Department of Civil Engineering  
Professor of Structural Engineering

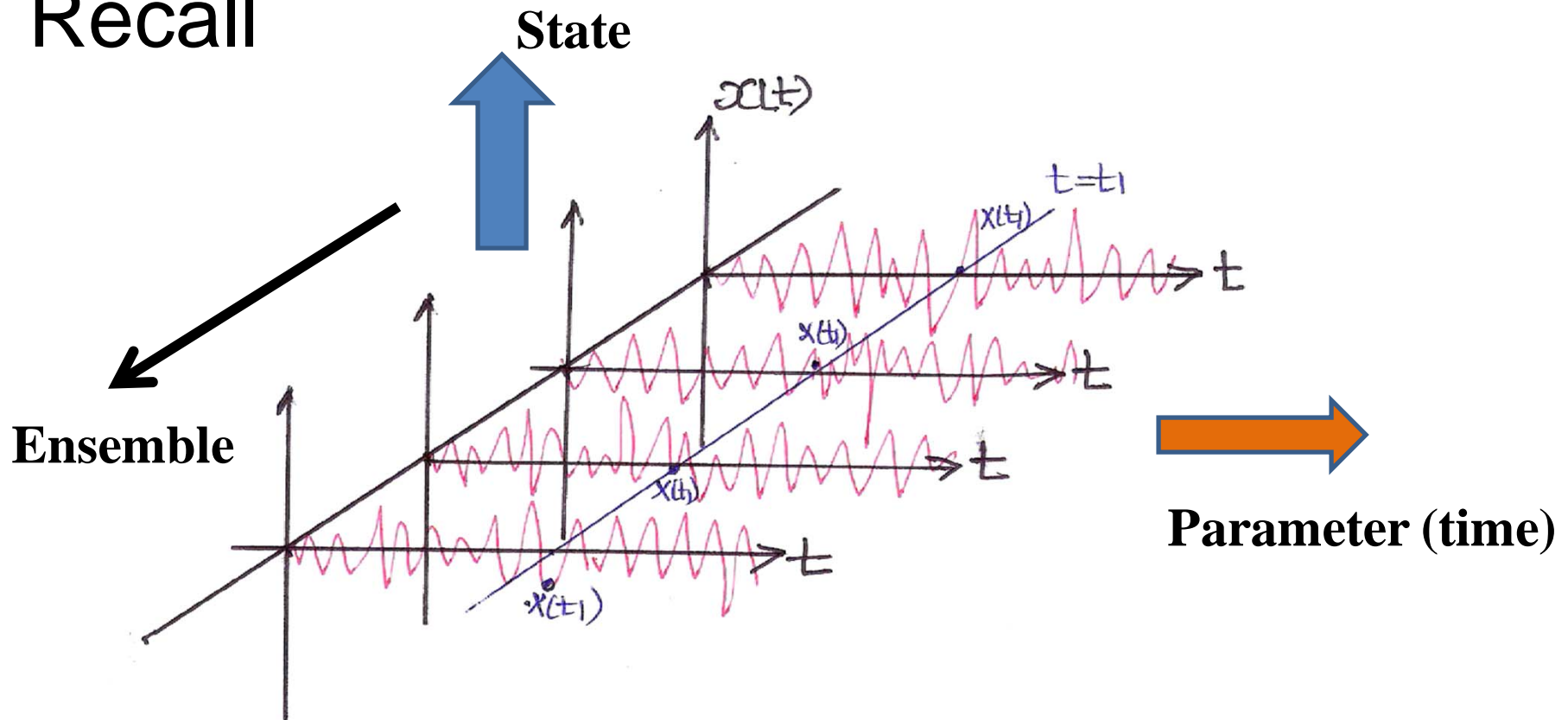
Indian Institute of Science

Bangalore 560 012 India

[manohar@civil.iisc.ernet.in](mailto:manohar@civil.iisc.ernet.in)



# Recall



Multi-dimensional PDF, pdf

Mean, covariance,...

Stationarity: SSS, WSS

Ergodicity: Temporal and ensemble average

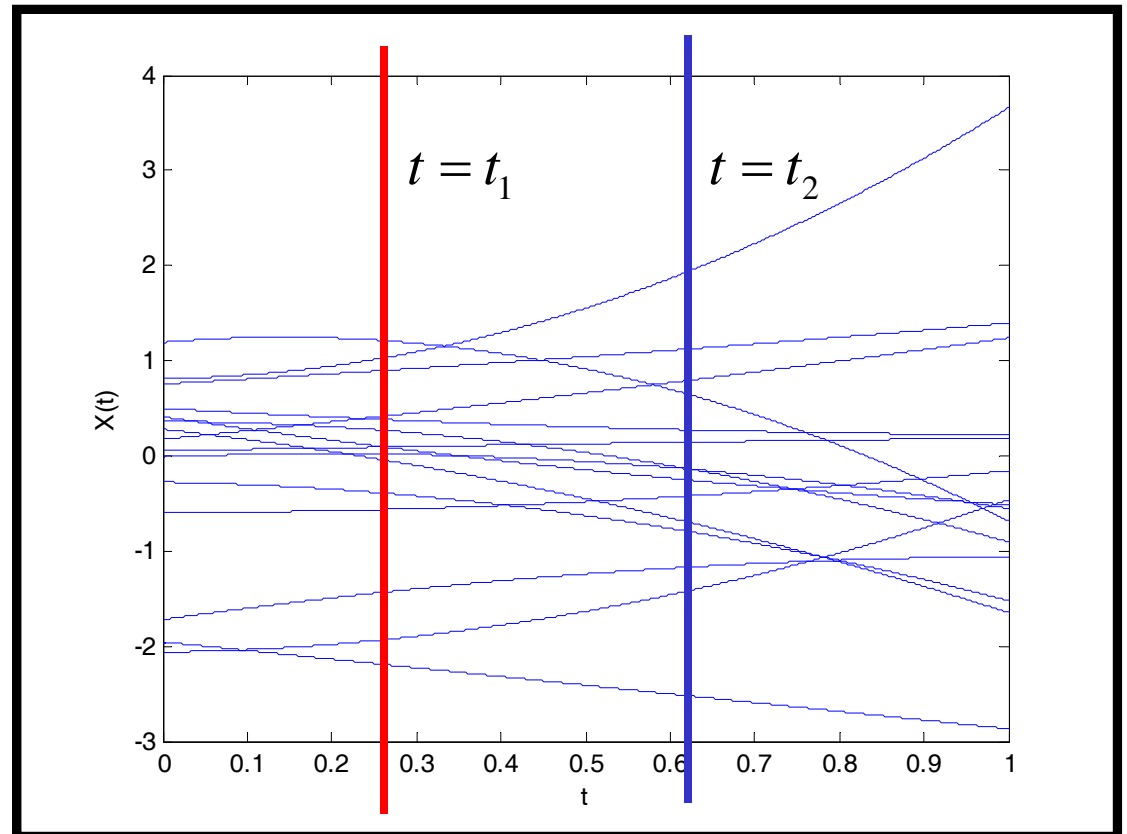
$$X(t) = a + bt + ct^2$$

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} \sim N \left[ \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right]$$

$$\langle X(t) \rangle = \langle a \rangle + \langle b \rangle t + \langle c \rangle t^2 = 0$$

$$\langle X(t_1) X(t_2) \rangle = a^2 + b^2 t_1 t_2 + c^2 t_1^2 t_2^2$$

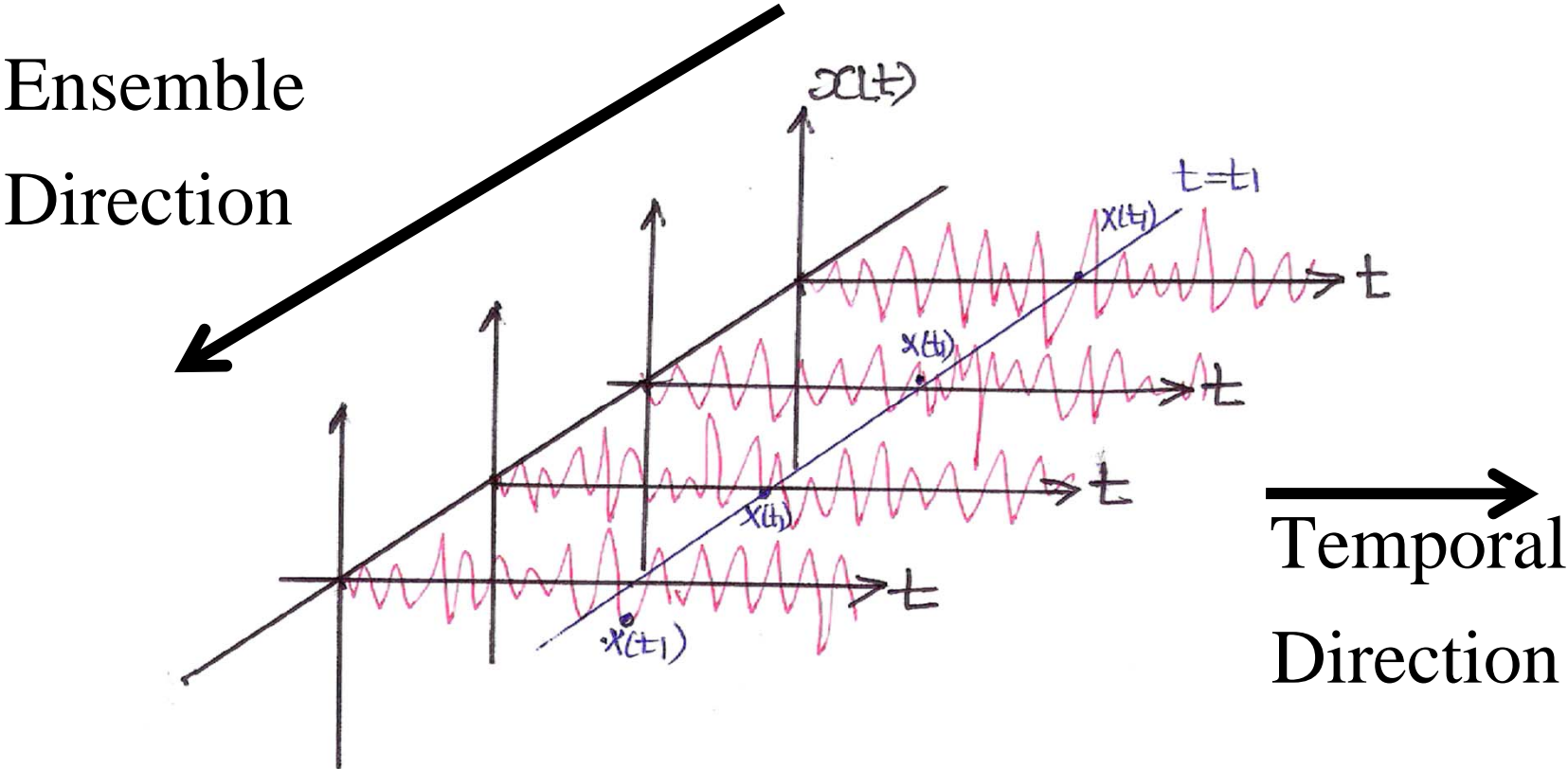
$$X(t) \sim N(0, a^2 + b^2 t^2 + c^2 t^4)$$



# Ergodicity of a random process

Basic notion

Equivalence of temporal and ensemble averages



Let  $x(t)$  be a sample realization of the random process  $X(t)$ . We define the time average of a given function of  $X(t)$ ,  $g[X(t)]$  by

$$T_{\text{av}}\{g[X(t)]\} = \frac{1}{T} \int_0^T g[x(t)] dt$$

If  $X(t)$  is an ergodic random process, then  $\langle g[X(t)] \rangle = T_{\text{av}}\{g[X(t)]\}$ .

## Definitions

- **Ergodicity in mean**  $X(t)$  is ergodic in mean if

$$T_{\text{av}}\{X(t)\} = \frac{1}{T} \int_0^T x(t) dt = \langle X(t) \rangle$$

- **Ergodicity in the mean square**  $X(t)$  is ergodic in meansquare if

$$T_{\text{av}}\{X^2(t)\} = \frac{1}{T} \int_0^T x^2(t) dt = \langle X^2(t) \rangle$$

- **Ergodicity in autocorrelation**  $X(t)$  is said to be ergodic in autocorrelation if

$$T_{\text{av}}\{X(t)X(t+\tau)\} = \frac{1}{T} \int_0^T x(t)x(t+\tau) dt = \langle X(t)X(t+\tau) \rangle = R_X(\tau)$$

## Remaraks

1. The above list of definitions of ergodicity are not exhaustive: several other similar definitions can be constructed by considering other descriptors of the random process.
2. Ergodic processes are necessarily stationary in nature; a stationary random process need not be ergodic.
3. Physically, ergodicity means that a sufficiently long record of a stationary random process contains all the statistical information about the random phenomenon.

## Ergodicity in mean

Let  $X(t)$  be a stationary random process with specified joint pdf structure

$$\eta_T = \frac{1}{2T} \int_{-T}^T X(t) dt$$

$\Rightarrow \eta_T$  is a random variable

$$E[\eta_T] = \frac{1}{2T} \int_{-T}^T E[X(t)] dt = E[x(t)] = \eta$$

$$\sigma_{\eta_T}^2 = \frac{1}{4T^2} \int_{-T}^T \int_{-T}^T E[\{X(t_1) - \eta\} \{X(t_2) - \eta\}] dt_1 dt_2$$

$$= \frac{1}{T} \int_0^{2T} \left(1 - \frac{\tau}{2T}\right) [R(\tau) - \eta^2] d\tau$$



## Ergodicity in mean

$X(t)$  is said to be ergodic in mean iff

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T X(t) dt = E[x(t)] = \eta$$

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^{2T} \left(1 - \frac{\tau}{2T}\right) [R(\tau) - \eta^2] d\tau \rightarrow 0$$

## Ergodicity in first order PDF

$$P_X(x, t) = P_X(x) = P[X(t) \leq x]$$

*Define*

$$y(t) = 1 \text{ if } X(t) \leq x$$

$$y(t) = 0 \text{ if } X(t) > x$$

$$\Rightarrow E[y(t)] = 1 \times P[X(t) \leq x] + 0 \times P[X(t) > x] = P_X(x)$$

$X(t)$  is said to be ergodic in first order PDF if  $y(t)$  is ergodic in mean

## Ergodicity in autocorrelation

*Define*

$$\phi(t) = X(t)X(t + \tau)$$

$$E[\phi(t)] = E[X(t)X(t + \tau)] = R_{XX}(\tau)$$

$X(t)$  is said to be ergodic in autocorrelation if  $\phi(t)$  is ergodic in mean

- Criteria for ergodicity in other properties could be developed on similar lines
- The above criteria are applicable if description of the random process is available.
- The notion of ergodicity plays a crucial role in relating observed data to mathematical models of uncertainties

# Frequency domain representation of functions of time

Let  $x(t)$  be a deterministic function of time

## Time signals

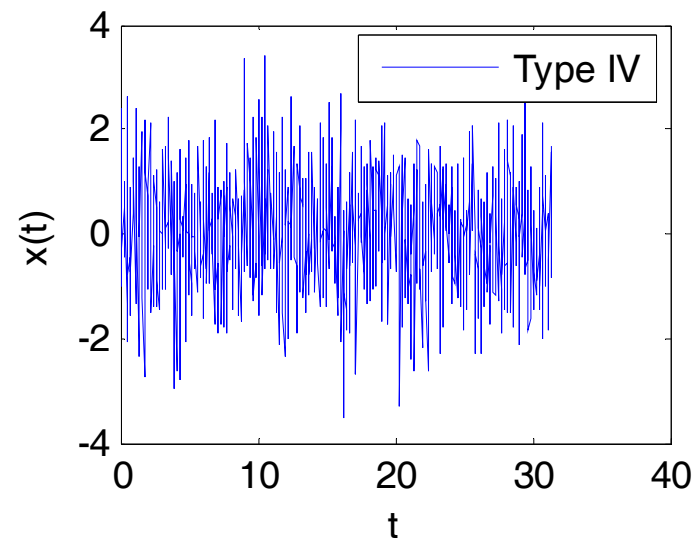
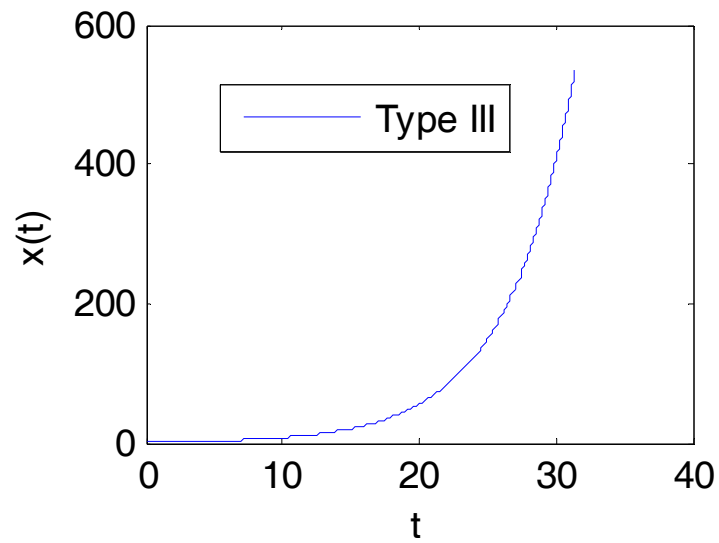
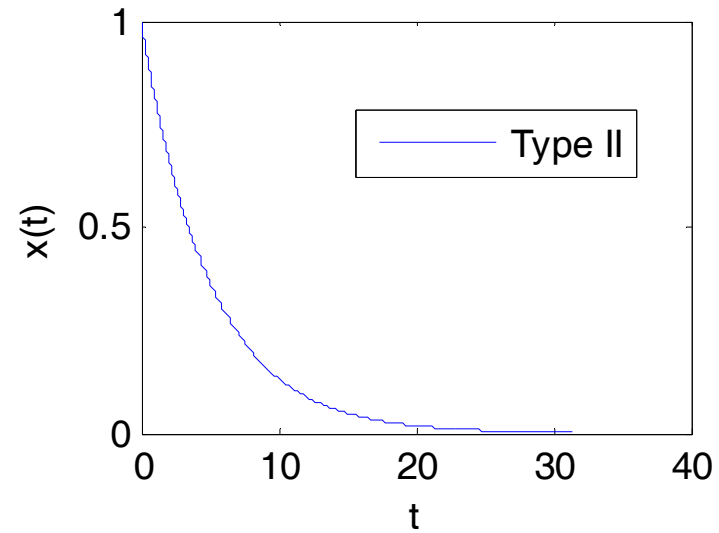
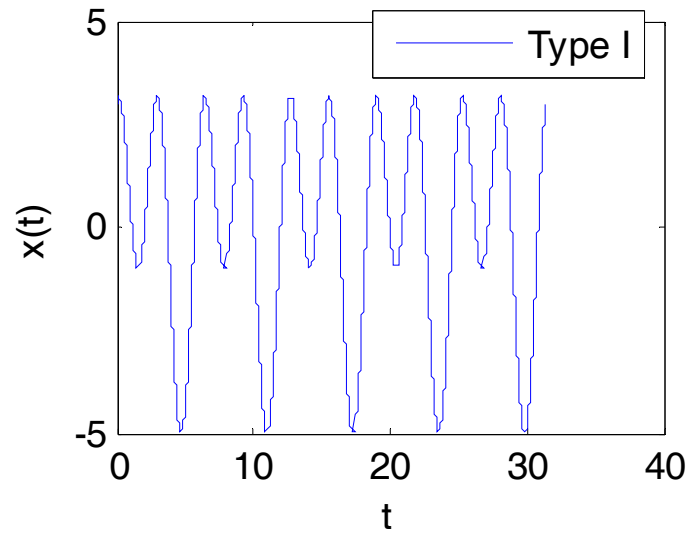
**Type I :** Periodic signals (well behaved)  $x(t \pm nT) = x(t)$

**Type II :** Aperiodic signals  $\lim_{t \rightarrow \infty} |x(t)| \rightarrow 0$

**Type III :** Aperiodic signals  $\lim_{t \rightarrow \infty} |x(t)| \rightarrow \infty$

**Type IV :** Aperiodic signals  $\lim_{t \rightarrow \infty} |x(t)|$  neither goes to zero nor becomes unbounded.

# A classification of time signals



## Remarks

Realizations of stationary random process belong to Type IV signals.

### **Type III signals**

No hope of any frequency domain representation.

# Type I functions

Periodic signals  $y(t) = y(t \pm nT)$

Period: the smallest value of  $T$  for which the above condition is valid.

$$y(t) = P \sin \lambda t = P \sin(\lambda t + 2\pi) = P \sin \lambda \left( t + \frac{2\pi}{\lambda} \right) \Rightarrow T = \frac{2\pi}{\lambda}$$

$$y(t) = P \cos \lambda t = P \cos(\lambda t + 2\pi) = P \cos \lambda \left( t + \frac{2\pi}{\lambda} \right) \Rightarrow T = \frac{2\pi}{\lambda}$$



$$\begin{aligned} y(t) &= P \cos \lambda t + Q \sin \lambda t = P \cos(\lambda t + 2\pi) + Q \sin(\lambda t) \\ &= P \cos \lambda \left( t + \frac{2\pi}{\lambda} \right) + Q \sin \lambda \left( t + \frac{2\pi}{\lambda} \right) \Rightarrow T = \frac{2\pi}{\lambda} \end{aligned}$$

$$\begin{aligned} y(t) &= P \cos 2\lambda t = P \cos(2\lambda t + 2\pi) \\ &= P \cos 2\lambda \left( t + \frac{2\pi}{2\lambda} \right) \Rightarrow T = \frac{\pi}{\lambda} \end{aligned}$$

$$\begin{aligned} y(t) &= P \cos \lambda t + Q \cos 2\lambda t \\ &= P \cos(\lambda t + 2\pi) + Q \cos(2\lambda t + 2\pi) \Rightarrow T = \frac{2\pi}{\lambda} \end{aligned}$$

$$y(t) = \sum_{n=1}^N a_n \cos\left(\frac{2\pi n}{T} t\right) + b_n \sin\left(\frac{2\pi n}{T} t\right) \Rightarrow$$

$Y(t)$  is periodic with period= $T$

According to Fourier's theorem, under general conditions, a periodic function  $y(t)$  can be represented by

$$y(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos\left(\frac{2\pi n}{T} t\right) + b_n \sin\left(\frac{2\pi n}{T} t\right)$$

$$a_n = \frac{2}{T} \int_{-T/2}^{T/2} y(t) \cos\left(\frac{2\pi n t}{T}\right) dt \quad \& \quad b_n = \frac{2}{T} \int_{-T/2}^{T/2} y(t) \sin\left(\frac{2\pi n t}{T}\right) dt; n = 1, 2, \dots, \infty$$

Recall

$$\cos \theta = \frac{1}{2} [\exp(i\theta) + \exp(-i\theta)] \quad \& \quad \sin \theta = \frac{1}{2i} [\exp(i\theta) - \exp(-i\theta)] \Rightarrow$$

$$y(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \left( \frac{\exp\left(i\frac{2\pi nt}{T}\right) + \exp\left(-i\frac{2\pi nt}{T}\right)}{2} \right) + b_n \left( \frac{\exp\left(i\frac{2\pi nt}{T}\right) - \exp\left(-i\frac{2\pi nt}{T}\right)}{2i} \right)$$

$$= \frac{a_0}{2} + \frac{1}{2} \sum_{n=1}^{\infty} \exp\left(i\frac{2\pi nt}{T}\right) (a_n - ib_n) + \exp\left(-i\frac{2\pi nt}{T}\right) (a_n + ib_n)$$

$$= \sum_{n=-\infty}^{\infty} \alpha_n \exp\left(i\frac{2\pi nt}{T}\right)$$

$$\alpha_n = \frac{a_n - ib_n}{2}; \quad \text{with} \quad a_{-n} = a_n; \quad b_{-n} = -b_n$$

$$\alpha_n = \frac{1}{T} \int_{-T/2}^{T/2} y(t) \exp\left(-i\frac{2\pi nt}{T}\right) dt$$

# sine, cosine, amplitude and phase spectra

$x(t)$  is periodic with period  $T$

$$x(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \{a_n \cos \omega_n t + b_n \sin \omega_n t\}; \quad \omega_n = \frac{2\pi n}{T}$$

$$a_n = \frac{2}{T} \int_0^T x(t) \cos \omega_n t dt \quad \& \quad b_n = \frac{2}{T} \int_0^T x(t) \sin \omega_n t dt$$

- The plots of  $a_n$  and  $b_n$  as a function of  $\omega_n$  are called, respectively, as the Fourier cosine and sine spectra.

- The plot of  $\sqrt{a_n^2 + b_n^2}$  as a function of  $\omega_n$  is called the Fourier amplitude spectrum.

- The plot of  $\tan^{-1} \left( \frac{b_n}{a_n} \right)$  as a function of  $\omega_n$  is called the Fourier phase spectrum.

## Energy and power of a signal

If  $x(t)$  is a displacement function,  $x^2(t)$  is a quantity that is proportional to potential energy.

Similarly, if  $x(t)$  is a velocity function,  $x^2(t)$  is a quantity that is proportional to kinetic energy.

We call  $\lim_{s \rightarrow \infty} \int_0^s x^2(t) dt$  as the total energy in the signal.

We call  $\frac{1}{T} \int_0^T x^2(t) dt$  as the energy per cycle (power) in the signal.

# Total energy and power

## Discrete power spectrum

Total energy:  $\lim_{s \rightarrow \infty} \int_0^s x^2(t) dt \rightarrow \infty \Rightarrow$

Total energy is not an useful concept.

Energy per cycle =  $\frac{1}{T} \int_0^T x^2(t) dt$  makes sense.

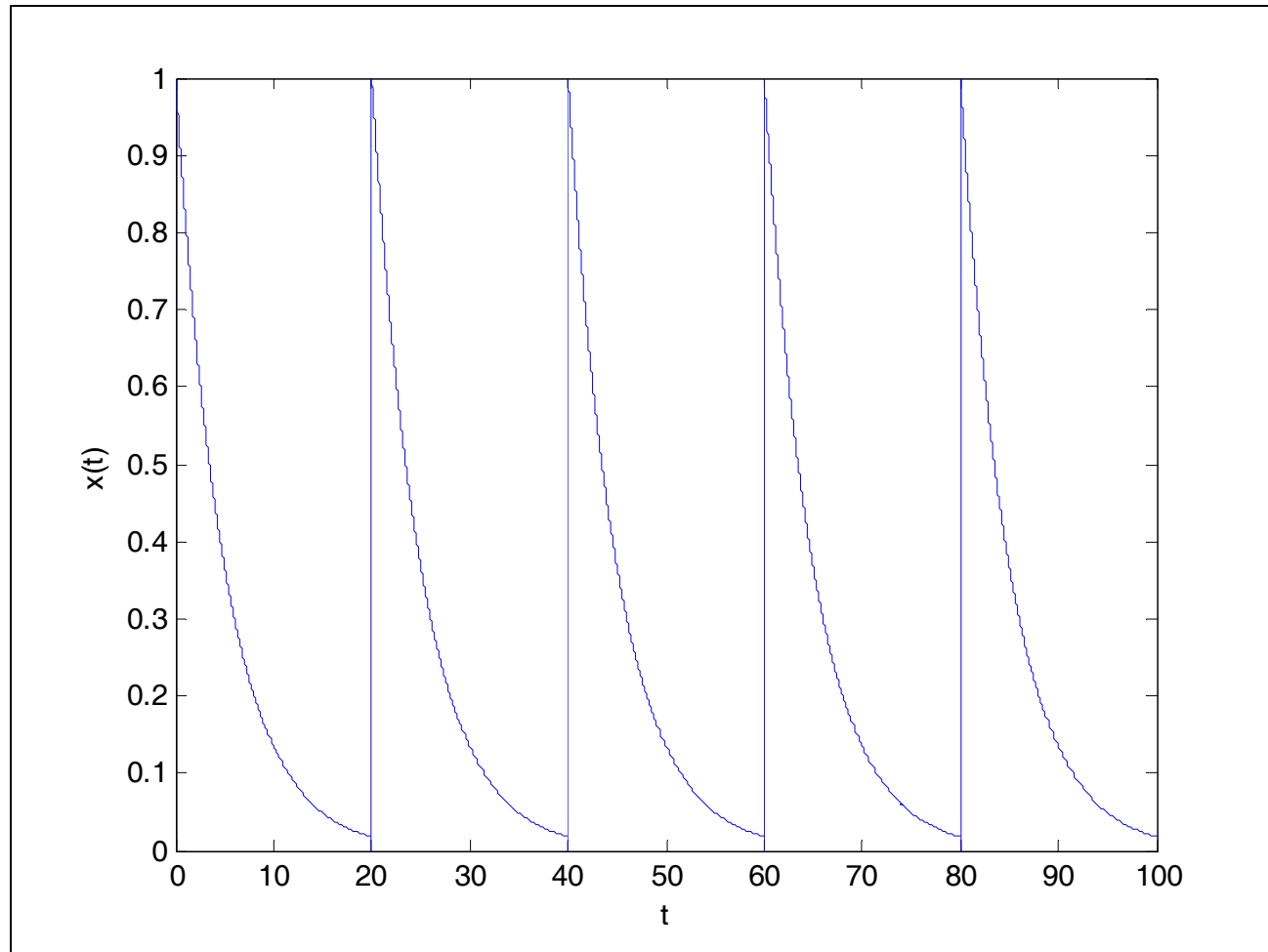
The plot of  $\frac{a_n^2 + b_n^2}{2}$  as a function of  $\omega_n$  is called the discrete power spectrum.

Discrete power spectrum is an useful concept for Type I signals.

# Type II signals

$$x_T(t) = x(t) \text{ for } 0 < t < T$$
$$x_T(t + nT) = x(t) \text{ for } n = 1, 2, \dots, \infty$$

$$x(t) = \exp(-0.2t)$$



$$x_T(t) = x(t) \text{ for } 0 < t < T$$
$$x_T(t + nT) = x(t) \text{ for } n = 1, 2, \dots, \infty$$

$x_T(t)$  belongs to Type I of time functions.  
 $\Rightarrow x_T(t)$  admits a Fourier series representation.

Clearly,  $\lim_{T \rightarrow \infty} x_T(t) \rightarrow x(t)$ .

Question: What happens to Fourier series based description of  $x_T(t)$  as  $T \rightarrow \infty$ ?



$$x_T(t) = \sum_{n=-\infty}^{\infty} \alpha_n \exp\left(\frac{i2\pi nt}{T}\right)$$

$$\alpha_n = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x_T(t) \exp\left(-\frac{i2\pi nt}{T}\right) dt$$

$$\begin{aligned} x_T(t) &= \sum_{n=-\infty}^{\infty} \left[ \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x_T(s) \exp\left(-\frac{i2\pi ns}{T}\right) ds \right] \exp\left(\frac{i2\pi nt}{T}\right) \\ &= \sum_{n=-\infty}^{\infty} \left[ \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x_T(s) \exp(-i2\pi n f_0 s) ds \right] \exp(i2\pi n f_0 t) \end{aligned}$$

$$x_T(t) = \sum_{n=-\infty}^{\infty} \left[ \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x_T(s) \exp(-i2\pi n f_0 s) ds \right] \exp(i2\pi n f_0 t)$$

$$f_0 = \frac{1}{T} \Rightarrow f_n = \frac{n}{T} \& f_{n+1} = \frac{n+1}{T}$$

$$\Rightarrow f_{n+1} - f_n = \frac{1}{T} = \Delta f_n = \Delta f$$

$$x_T(t) = \sum_{n=-\infty}^{\infty} \left[ \int_{-\frac{T}{2}}^{\frac{T}{2}} x_T(s) \exp(-i2\pi n f_0 s) ds \right] \exp(i2\pi n f_0 t) \Delta f_n$$

$$= \sum_{n=-\infty}^{\infty} X(f_n) \exp(i2\pi n f_0 t) \Delta f_n$$

$$\lim_{\Delta f_n \rightarrow \infty} x_T(t) \rightarrow x(t) = \int_{-\infty}^{\infty} X(f) \exp(i2\pi f t) df$$

## Definition: Fourier Transform pair

$x(t)$  is aperiodic;  $\lim_{t \rightarrow \infty} |x(t)| \rightarrow 0$

$$x(t) = \int_{-\infty}^{\infty} X(f) \exp[i2\pi ft] df$$

$$X(f) = \int_{-\infty}^{\infty} x(t) \exp[-i2\pi ft] dt$$

Power =  $\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T x^2(t) dt \rightarrow 0$  and hence not useful.

Total energy =  $\lim_{s \rightarrow \infty} \int_0^s x^2(t) dt \rightarrow$  could be an useful quantity.

Energy spectrum is an useful concept

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) \exp(i\omega t) d\omega$$

$$X(\omega) = \int_{-\infty}^{\infty} x(t) \exp(-i\omega t) dt$$

*x(t) and X(ω) are said to form a Fourier transform pair*

## Parseval theorem

$$\int_{-\infty}^{\infty} x^2(t) dt = \int_{-\infty}^{\infty} x(t) \left[ \int_{-\infty}^{\infty} X(f) \exp(i2\pi ft) df \right] dt$$

$$= \int_{-\infty}^{\infty} X(f) \left[ \int_{-\infty}^{\infty} x(t) \exp(-i2\pi ft) dt \right] df$$

$$= \int_{-\infty}^{\infty} X(f) X^*(f) df$$

$$\Rightarrow \int_{-\infty}^{\infty} x^2(t) dt = \int_{-\infty}^{\infty} |X(f)|^2 df$$

## Type III time functions

$$\lim_{t \rightarrow \infty} |x(t)| \rightarrow \infty$$

**No hope of any frequency  
domain representations**

## Type IV

Define  $x_T(t) = x(t)$  for  $0 < t \leq T$  &  
 $= 0$  for  $t > T$

$$X_T(\omega) = \int_{-\infty}^{\infty} x_T(t) \exp(-i\omega t) dt$$

$$x_T(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X_T(\omega) \exp(i\omega t) d\omega$$

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T |X_T(f)|^2 df = \text{Total power}$$

$$\Rightarrow h(f) = \lim_{T \rightarrow \infty} \frac{1}{T} |X_T(f)|^2 = \text{power spectral density function.}$$

$\Rightarrow h(f) df =$  contribution to the total power made

by the frequency components in the range  $(f, f + df)$ .

Type V:  $x(t)$  is a stationary random process

Let  $X(t)$  be a zero mean stationary random process.

Samples of  $X(t)$  belong to Type IV time histories.

$\Rightarrow$  For each sample the power spectral density function can be defined.

**Definition:**

Power spectral density function of  $X(t)$

$$S_{XX}(f) = \lim_{T \rightarrow \infty} \frac{1}{T} \left\langle \left| X_T(f) \right|^2 \right\rangle$$



$$\begin{aligned}
S_{XX}(\omega) &= \lim_{T \rightarrow \infty} \frac{1}{T} \left\langle X_T(\omega) X_T^*(\omega) \right\rangle \\
&= \lim_{T \rightarrow \infty} \frac{1}{T} \left\langle \int_0^T X(t) \exp(-i\omega t) dt \int_0^T X(t) \exp(i\omega t) dt \right\rangle \\
&= \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \int_0^T \langle X(t_1) X(t_2) \rangle \exp[i\omega(t_2 - t_1)] dt_1 dt_2 \\
&= \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \int_0^T R_{XX}(t_2 - t_1) \exp[i\omega(t_2 - t_1)] dt_1 dt_2 \\
&= \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T}^T [T - |\tau|] R_{XX}(\tau) \exp(i\omega\tau) d\tau
\end{aligned}$$

If we restrict our attention to only those  $R_{XX}(\tau)$  which satisfy the condition

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T}^T |\tau| R_{XX}(\tau) \exp(i\omega\tau) d\tau \rightarrow 0,$$

we get the relations

$$S_{XX}(\omega) = \int_{-\infty}^{\infty} R_{XX}(\tau) \exp(i\omega\tau) d\tau$$

$$R_{XX}(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_{XX}(\omega) \exp(-i\omega\tau) d\omega$$

## Remarks

$$(1) R_{XX}(\tau) = \langle X(t)X(t+\tau) \rangle = \langle X(t)X(t-\tau) \rangle = R_{XX}(-\tau)$$

$$(2) S_{XX}(\omega) = \int_{-\infty}^{\infty} R_{XX}(\tau) \exp(i\omega\tau) d\tau$$

$$= \int_{-\infty}^{\infty} R_{XX}(\tau) (\cos \omega\tau + i \sin \omega\tau) d\tau$$

$$= \int_{-\infty}^{\infty} R_{XX}(\tau) \cos \omega\tau d\tau \quad \left\{ \because R_{XX}(\tau) = R_{XX}(-\tau) \right\}$$

$$= 2 \int_0^{\infty} R_{XX}(\tau) \cos \omega\tau d\tau$$

## Remarks

$$(3) R_{XX}(0) = \sigma_X^2 = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_{XX}(\omega) d\omega.$$

$\Rightarrow$  Area under the PSD function is the variance of the process.

(4)  $S_{XX}(\omega) d\omega$  = contribution to the total average power (variance) made by frequency components in the range  $(\omega, \omega + d\omega)$ .

$$\Rightarrow S_{XX}(\omega) \geq 0$$

$$(5) S_{XX}(-\omega) = \int_{-\infty}^{\infty} R_{XX}(\tau) \exp(-i\omega\tau) d\tau \quad (\text{Substitute } s = -\tau)$$

$$= \int_{-\infty}^{\infty} R_{XX}(-s) \exp(i\omega s) ds$$

$$= \int_{-\infty}^{\infty} R_{XX}(s) \exp(i\omega s) ds = S_{XX}(\omega)$$

## Remarks

$$\begin{aligned}(6) R_{XX}(\tau) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} S_{XX}(\omega) \exp(-i\omega\tau) d\omega \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} S_{XX}(\omega) (\cos \omega\tau + i \sin \omega\tau) d\omega \\ &= \frac{1}{\pi} \int_0^{\infty} S_{XX}(\omega) \cos \omega\tau d\omega\end{aligned}$$

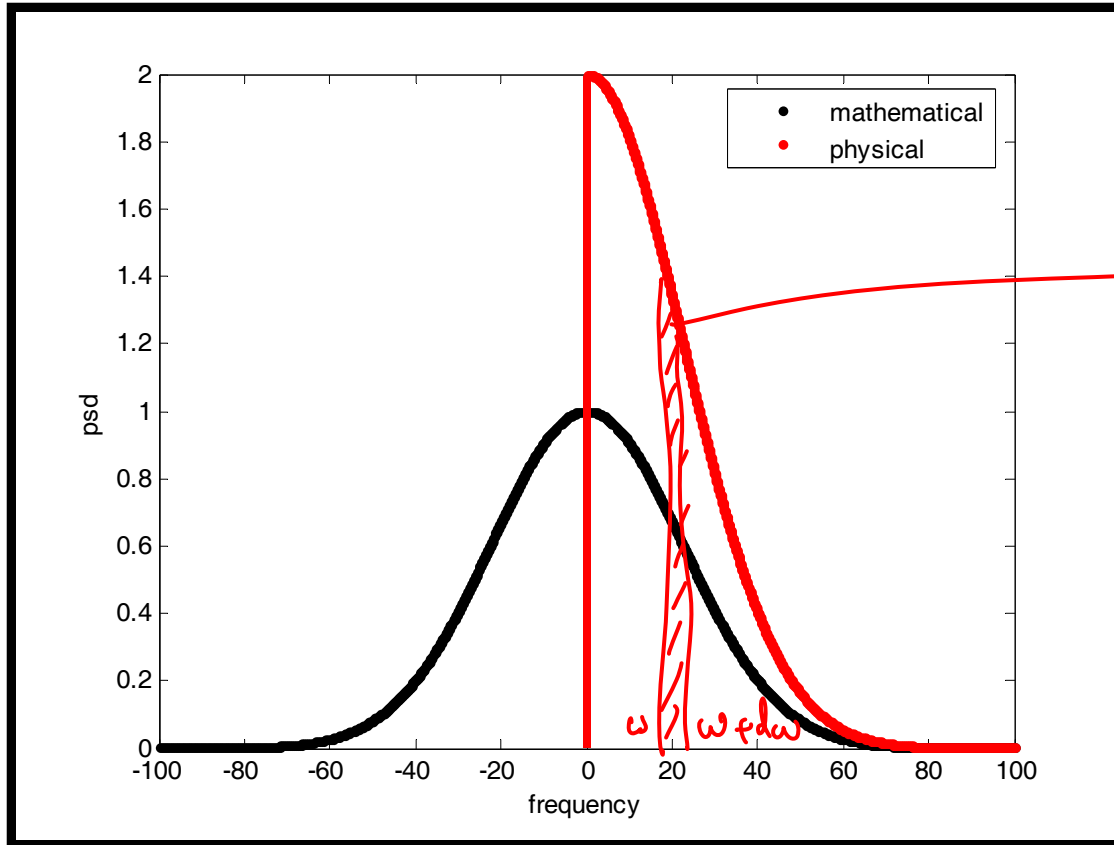
(7) Physical PSD function (defined only for  $\omega \geq 0$ )

$$\begin{aligned}G_{XX}(\omega) &= 2S_{XX}(\omega) \quad \text{for } \omega \geq 0 \\ &= 0 \quad \text{for } \omega < 0\end{aligned}$$

Area under  $G_{XX}(\omega)$  would still be the variance of the process.

# PSD

$\frac{S_{XX}(\omega)}{\sigma_X^2}$  has properties similar to a pdf



$f(\omega)d\omega$   
= Contribution  
to variance  
by freq components  
in  $\omega$  to  $\omega+d\omega$

Units of PSD:  $\frac{[\text{Units of } X(t)]^2}{\text{frequency}}$

Ex:  $X(t)$  is displacement

Units of PSD :  $\frac{\text{m}^2}{\text{Hz}}$  or  $\frac{\text{m}^2}{(\text{rad/s})}$

Similarly, if  $X(t)$  is acceleration

Units of PSD:  $\frac{(\text{m/s}^2)^2}{\text{Hz}}$  or  $\frac{(\text{m/s}^2)^2}{(\text{rad/s})}$

## Remarks

(8) Wiener-Khinchine relations

$$S_{XX}(\omega) = 2 \int_0^{\infty} R_{XX}(\tau) \cos \omega \tau d\tau$$

$$R_{XX}(\tau) = \frac{1}{\pi} \int_0^{\infty} S_{XX}(\omega) \cos \omega \tau d\omega$$

$\Rightarrow$

$$G_{XX}(\omega) = 4 \int_0^{\infty} R_{XX}(\tau) \cos \omega \tau d\tau$$

$$R_{XX}(\tau) = \frac{1}{2\pi} \int_0^{\infty} G_{XX}(\omega) \cos \omega \tau d\omega$$



## A few examples of covariance and psd function pairs

$$R(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S(\omega) \exp(j\omega\tau) d\omega \quad S(\omega) = \int_{-\infty}^{\infty} R(\tau) \exp(-j\omega\tau) d\tau$$

$$\delta(\tau)$$

$$1$$

$$\exp(j\beta\tau)$$

$$2\pi\delta(\omega - \beta)$$

$$1$$

$$2\pi\delta(\omega)$$

$$\cos \beta\tau$$

$$\pi\delta(\omega - \beta) + \pi\delta(\omega + \beta)$$

$$\exp(-\alpha|\tau|)$$

$$\frac{2\alpha}{\alpha^2 + \omega^2}$$

$$\exp(-\alpha\tau^2)$$

$$\sqrt{\frac{\pi}{\alpha}} \exp\left(-\frac{\omega^2}{4\alpha}\right)$$

$$\exp(-\alpha|\tau|) \cos \beta\tau$$

$$\frac{\alpha}{\alpha^2 + (\omega - \beta)^2} + \frac{\alpha}{\alpha^2 + (\omega + \beta)^2}$$

$$2 \exp(-\alpha\tau^2) \cos \beta\tau$$

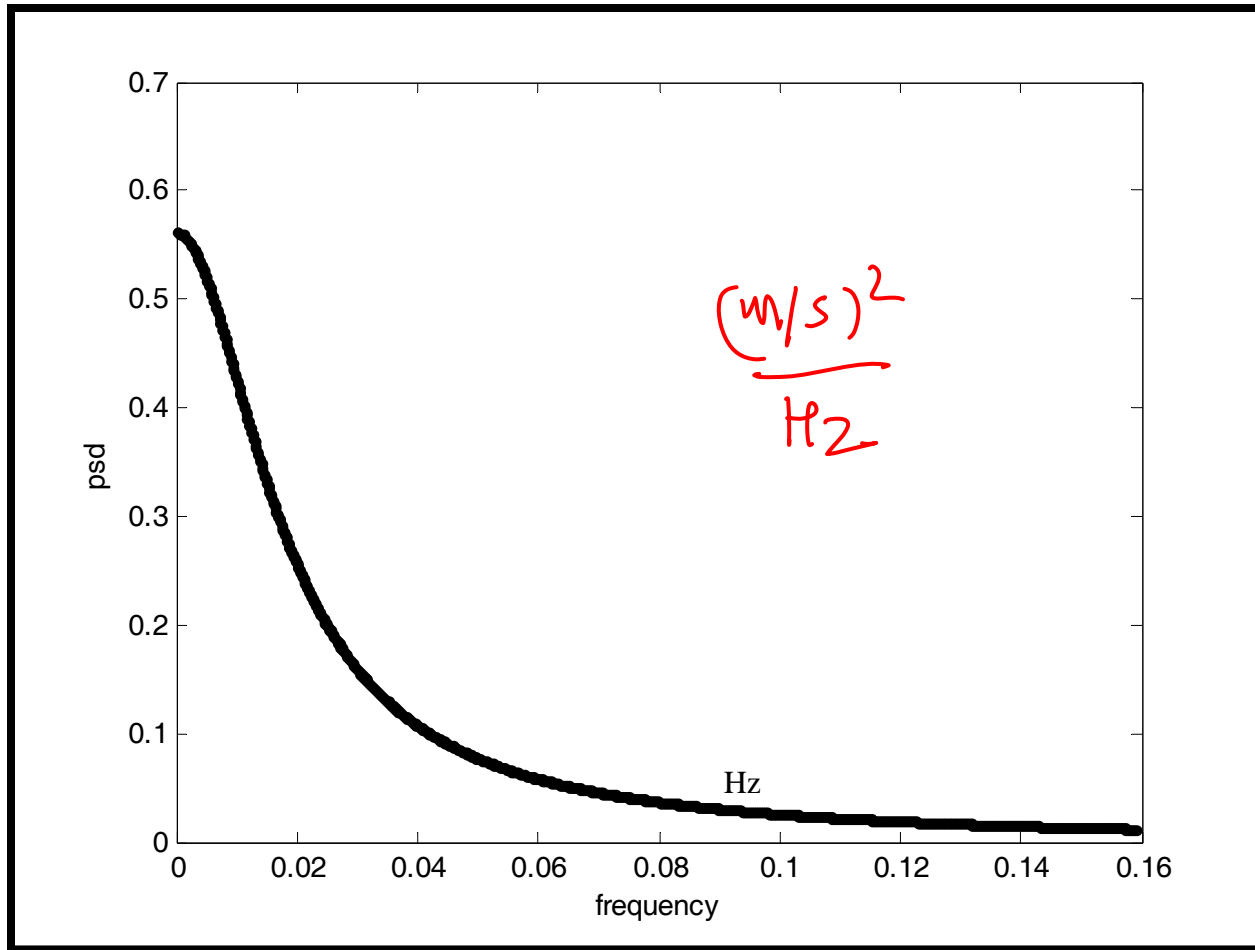
$$\sqrt{\frac{\pi}{\alpha}} \left\{ \exp\left(-\frac{(\omega - \beta)^2}{4\alpha}\right) + \exp\left(-\frac{(\omega + \beta)^2}{4\alpha}\right) \right\}$$

$$\frac{\sin \sigma\tau}{\pi\tau}$$

$$\begin{cases} 1 & |\omega| < \sigma \\ 0 & |\omega| > \sigma \end{cases}$$

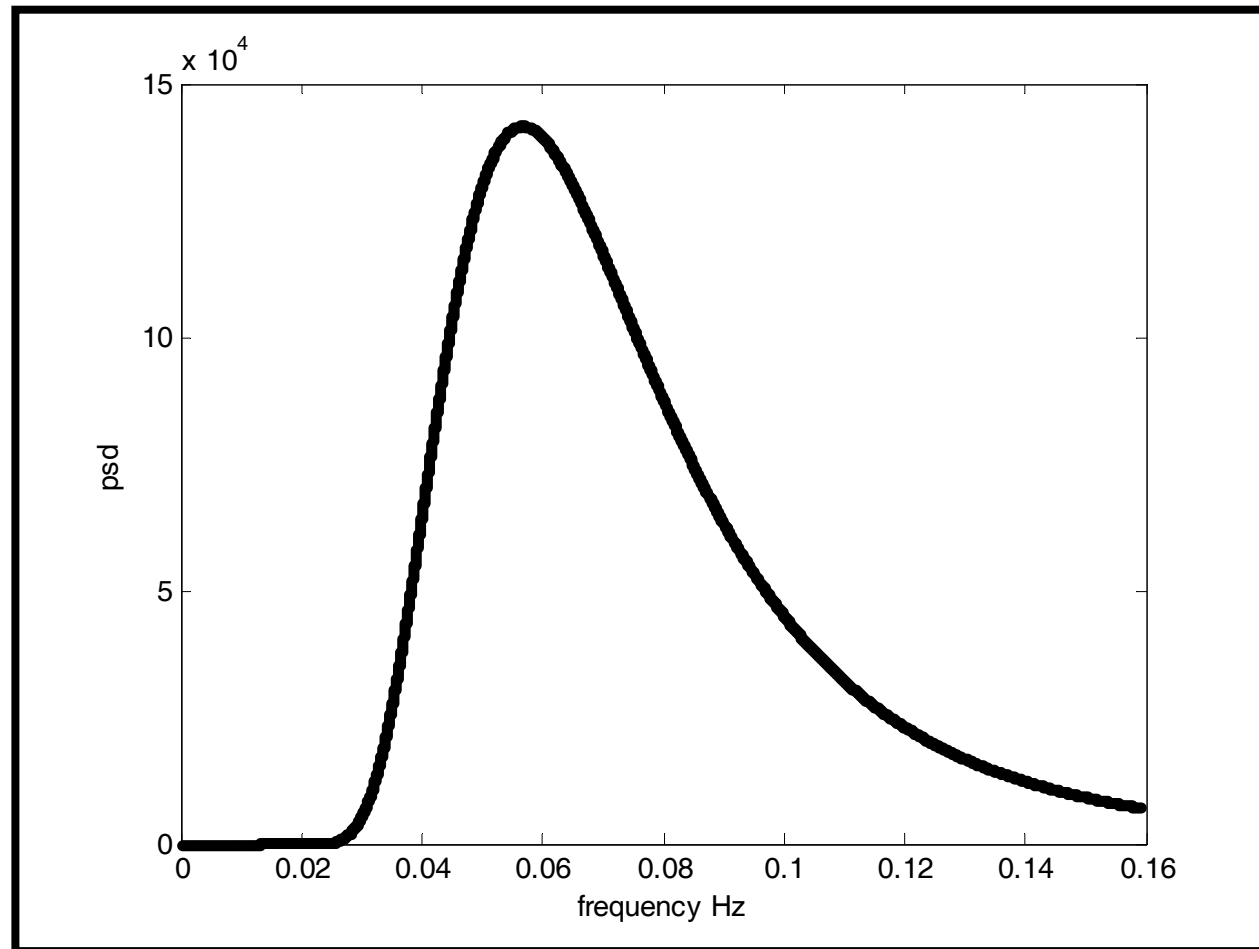
# Typical psd function of wind velocity

$$G(\omega) = c_0 \frac{1}{\left[2 + \left(\frac{873.6\omega}{u_0}\right)^2\right]^{\frac{5}{6}}}$$

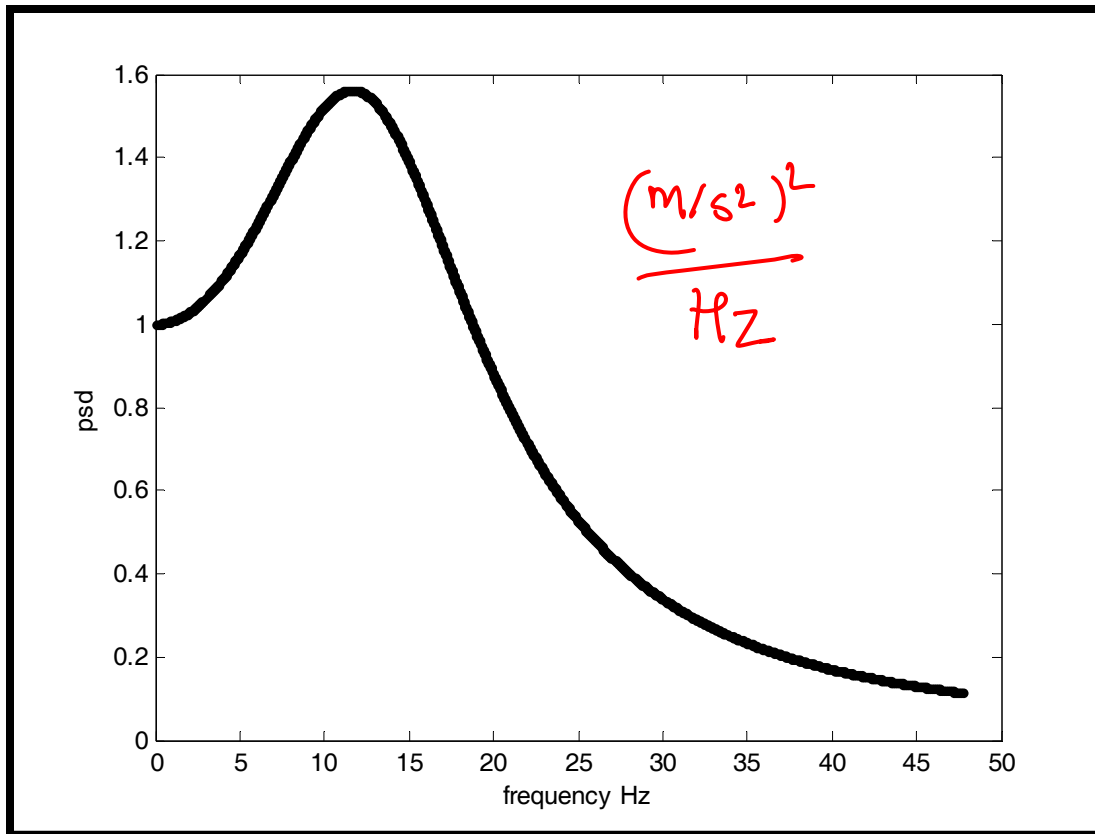


Typical psd function of waves

$$G(\omega) = c_0 \frac{1}{\omega^5} \exp\left(-\frac{c_1}{\omega^4}\right)$$



# Typical psd function of earthquake ground acceleration



$$G(\omega) = c_0 \frac{1 + \left(\frac{\omega}{\omega_g}\right)^2}{\left[1 - \left(\frac{\omega}{\omega_g}\right)^2\right]^2 + 4\eta_g^2 \left(\frac{\omega}{\omega_g}\right)^2}$$

## Evolutionary random process

Consider a random process  $X(t)$  defined as

$$X(t) = V_1(t) \text{ if } 0 < t < t_1$$

$$\& X(t) = V_2(t) \text{ if } t > t_1.$$

Let  $V_1(t)$  &  $V_2(t)$  be zero mean, stationary random processes

with psd functions  $\{S_{V_i}(\omega)\}_{i=1}^2$ .

$\Rightarrow$  We can write

$$S_{XX}(\omega, t) = S_{V_1}(\omega) \text{ if } 0 < t < t_1$$

$$S_{XX}(\omega, t) = S_{V_2}(\omega) \text{ if } t > t_1$$

This notion can be generalized to define nonstationary random processes with time dependent psd functions.

Such processes are called as evolutionary random processes.