

NPTEL Course

GROUND IMPROVEMENT

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Deep Compaction and Objectives

Compaction

>Deep compaction techniques are required when in—situ soil extending to large depths does not meet the requirements of performance criteria specified for the expected loading and environmental conditions.

Deep soil improvement is possible by resorting to

- Ground Improvement Techniques
- Ground Reinforcement Techniques
- Ground treatment

Ground Improvement

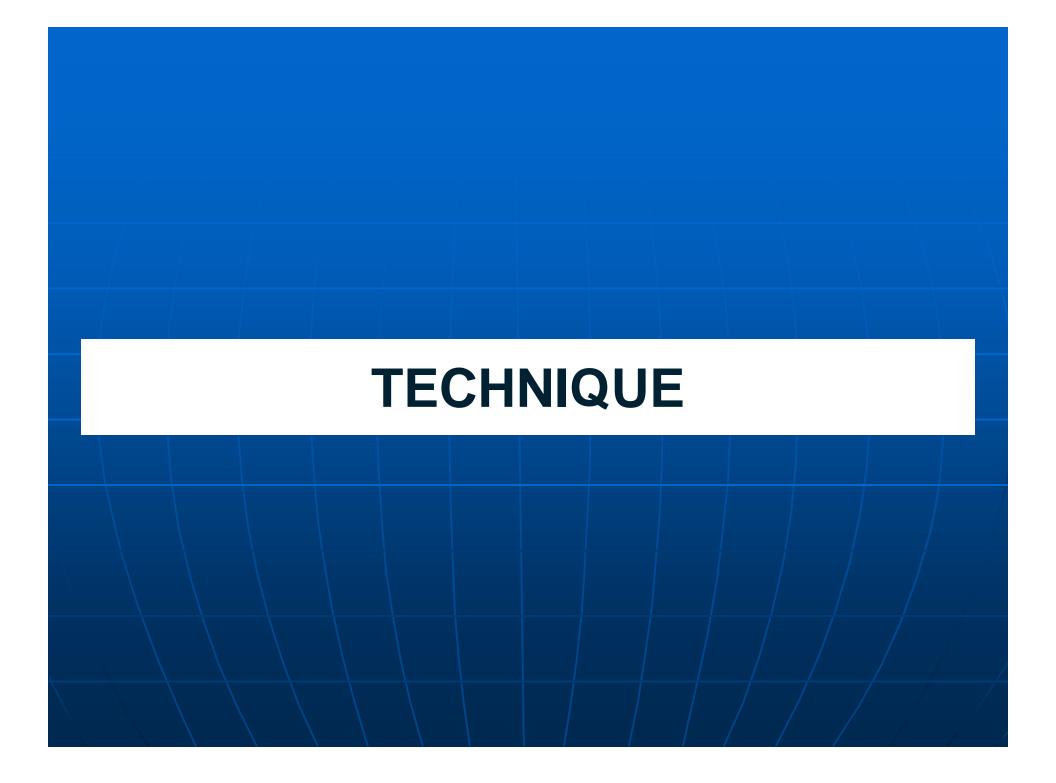
Dynamic Compaction
Vibro-Compaction
Compaction Grouting
Pre-fabricated Vertical Drains
Blast densification

Dynamic Compaction



Format

- > Technique
- > Energy transfer mechanism
- Stages of compaction
- Application which soils are compacted?
- > Types
- Ground Vibrations
- > Design Considerations

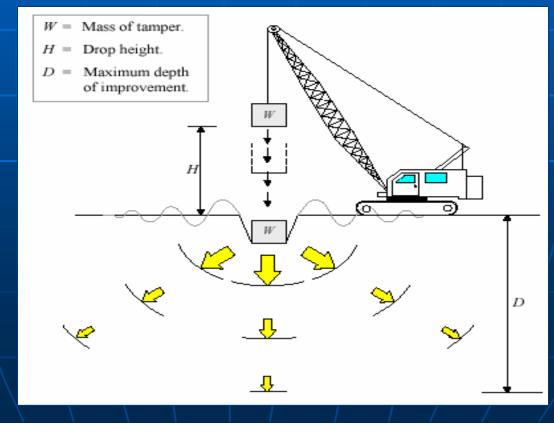


- Fechnique involves repeatedly dropping a large weight from a crane
- Weight may range from 6 to 172 tons
- > Drop height typically varies from 10 m to 40 m

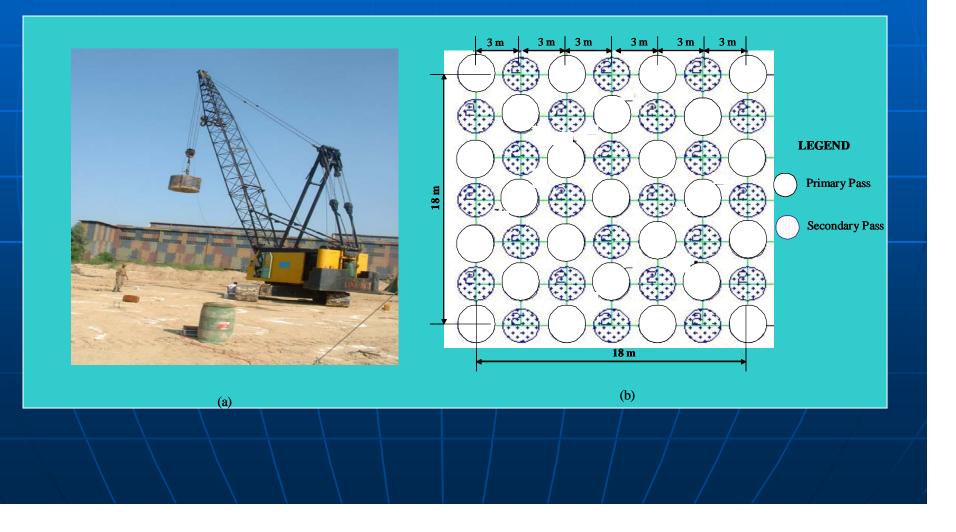


Degree of densification achieved is a function of the energy input (weight and drop height) as well as the saturation level, fines content and permeability of the material

6 – 30 ton weight can densify the loose sands to a depth of 3 m to 12 m

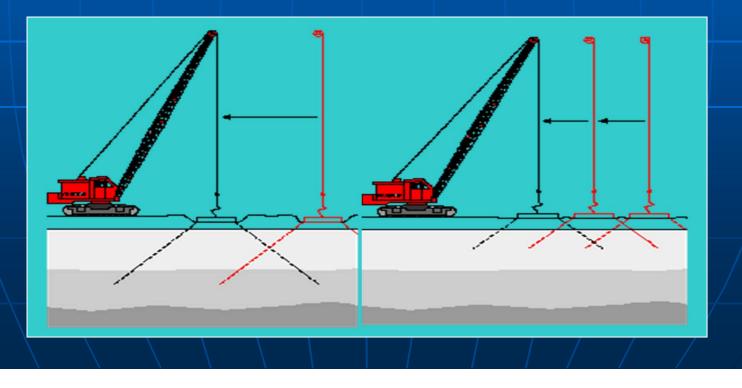


- Done systematically in a rectangular or triangular pattern in phases
- Each phase can have no of passes; primary, secondary, tertiary, etc.



Spacing between impact points depend upon:
Depth of compressible layer
Permeability of soil
Location of ground water level

Deeper layers are compacted at wider grid spacing, upper layers are compacted with closer grid spacing

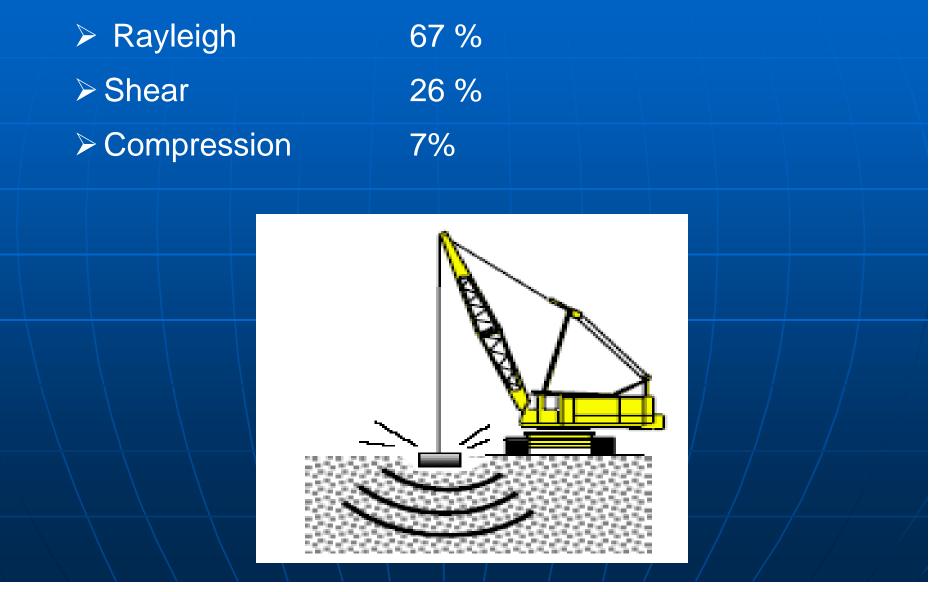


- Deep craters are formed by tamping
- Craters may be filled with sand after each pass
- Heave around craters is generally small



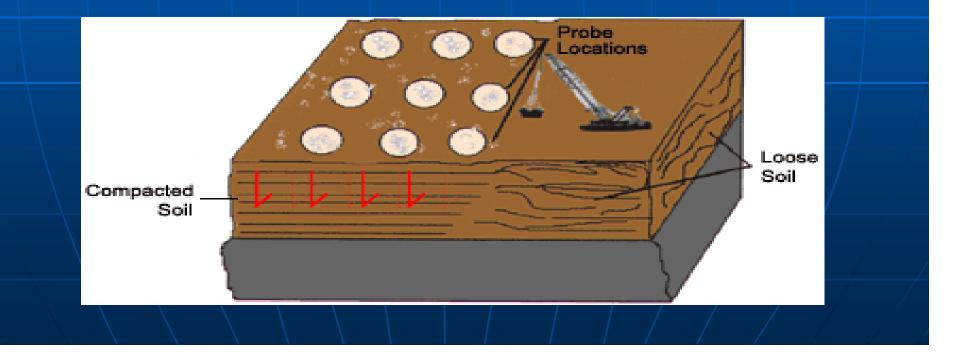
ENERGY TRANSFER MECHANISM

Energy transferred by propagation of Rayleigh (surface) waves and volumic (shear and compression) waves



DENSIFICATION PROCESS

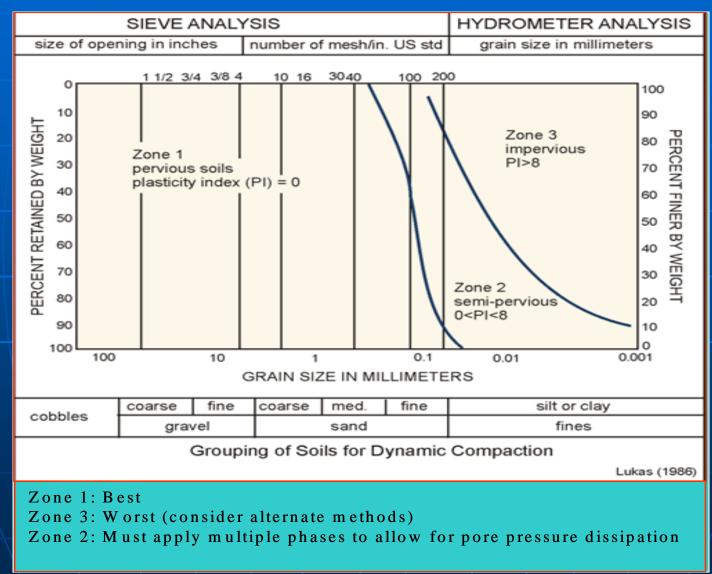
- Compressibility of saturated soil due to presence of micro bubbles
- Gradual transition to liquefaction under repeated impacts
- Rapid dissipation of pore pressures due to high permeability after soil fissuring
- > Thixotropic recovery



APPLICATION

> Applicable to wide variety of soils

Grouping of soils on the basis of grain sizes



- Mainly used to compact granular fills
- Particularly useful for compacting rockfills below water and for bouldery soils where other methods can not be applied or are difficult
- Waste dumps, sanitary landfills, and mine wastes





In sanitary fills, settlements are caused either by compression of voids or decaying of the trash material over time, DDC is effective in reducing the void ratio, and therefore reducing the immediate and long term settlement.

- DDC is also effective in reducing the decaying problem, since collapse means less available oxygen for decaying process.
- For recent fills where organic decomposition is still underway, DDC increases the unit weight of the soil mass by collapsing voids and decreasing the void ratio.
- For older fills where biological decomposition is complete, DDC has greatest effects by increasing unit weight and reducing long term ground subsidence.

TYPES OF DYNAMIC COMPACTION

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- > Dynamic compaction
- > Dynamic consolidation
- > Dynamic replacement
- Rotational dynamic compaction
- Rapid impact dynamic compaction

Dynamic Compaction

It is the compaction of unsaturated or highly permeable saturated granular materials by heavy tamping

The response to tamping is immediate

Dynamic Consolidation

➤The improvement by heavy tamping of saturated cohesive materials in which the response to tamping is largely time dependent

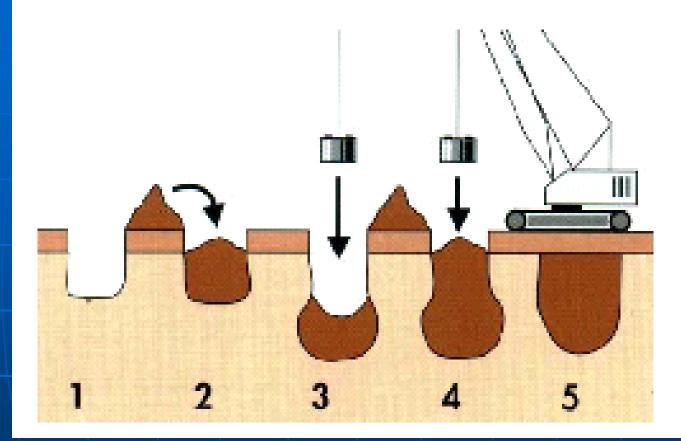
Excess pore water pressures are generated as a result of tamping and dissipate over several hours or days after tamping.

Dynamic Replacement

The formation by heavy tamping of large pillars of imported granular soil within the body of soft saturated soil to be improved

The original soil is highly compressed and consolidated between the pillars and the excess pore pressure generated requires several hours to dissipate

The pillars are used both for soil reinforcement and drainage



Process of Dynamic Replacement

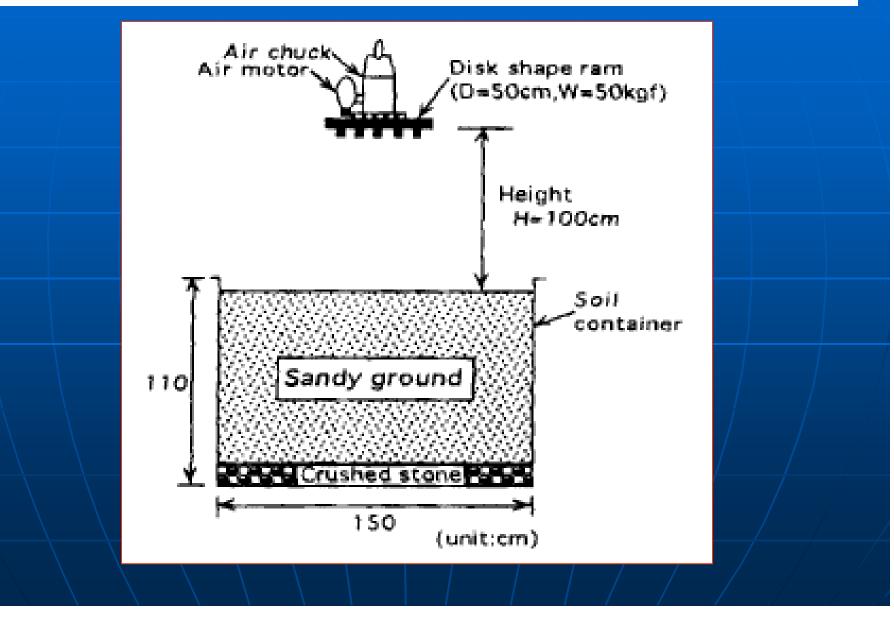
Rotational Dynamic Compaction

>A new dynamic compaction technique which makes use of the free fall energy as well as rotational energy of the tamper called Rotational Dynamic Compaction (RDC)

>The technique increases depth of improvement in granular soils

Comparative study showed that the cone penetration resistance was generally larger than conventional dynamic compaction and the tamper penetration in rotational dynamic compaction was twice as large as that of conventional dynamic compaction

Rotational Dynamic Compaction



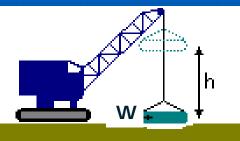
Rapid Impact Dynamic Compaction



EVALUATION OF IMPROVEMENT

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The depth of improvement is proportional to the energy per blow



The improvement can be estimated through empirical correlation, at design stage and is verified after compaction through field tests such as Standard Penetration Tests (SPT), Cone Penetration Test (CPT), etc. $D_{max} = n\sqrt{W \times H}$ Where,

 D_{max} = Max depth of improvement, m

n = Coefficient that caters for soil and equipment variability

W = Weight of tamper, tons

H = Height of fall of tamper, m

The effectiveness of dynamic compaction can also be assessed readily by the crater depth and requirement of backfill

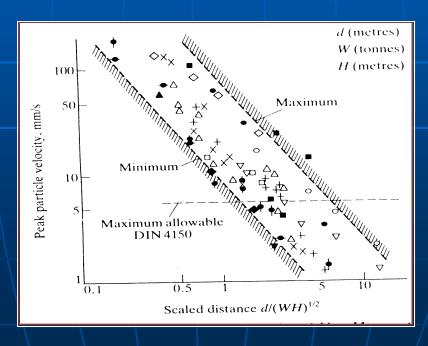
Reference	N-Values
Menard and Broise (1975)	1.0
Leonard et al. (1980)	0.5
Bjolgerud and Han (1963)	1.0 (rockfill)
Smoltcyk (1983)	0.5 (soil with unstable structure)0.67 (silts and sands)1.0 (purely frictional sand)
Lukas (1980)	0.65 - 0.8
Mayne et al. (1984)	0.3 - 0.8
Gambin (1984) Qian (1985)	0.5 – 1.0 0.65 (fine sand) 0.66 (soft clay) 0.55 (loess)
Van Impe (1989)	0.65 (silty sand) 0.5 (clayey sand)

GROUND VIBRATIONS

- Dynamic compaction generates surface waves with a dominant frequency of 3 to 12 Hz
- These vibrations generate compression, shear and Rayleigh waves
- The Raleigh waves contain about 67 percent of the total vibration energy and become predominant over other wave types at comparatively small distances from the source
- Raleigh waves have the largest practical interest for the design engineers because building foundations are placed near the ground surface

- The ground vibrations are quantified in terms of peak particle velocity (PPV); the maximum velocity recorded in any of the three coordinate axes
- The measurement of vibrations is necessary to determine any risk to nearby structures
- The vibrations can be estimated through empirical correlations or measured with the help of instruments such as portable seismograph, accelerometers, velocity transducers, linear variable displacement transducers (LVDT), etc.

- The frequency of the Raleigh waves decreases with increasing distance from the point of impact
- Relationship between PPV and inverse scaled distance is shown graphically (the inverse scaled distance is the square root of the compaction energy, divided by the distance, d from the impact point)



Tolerance Limits for Structures

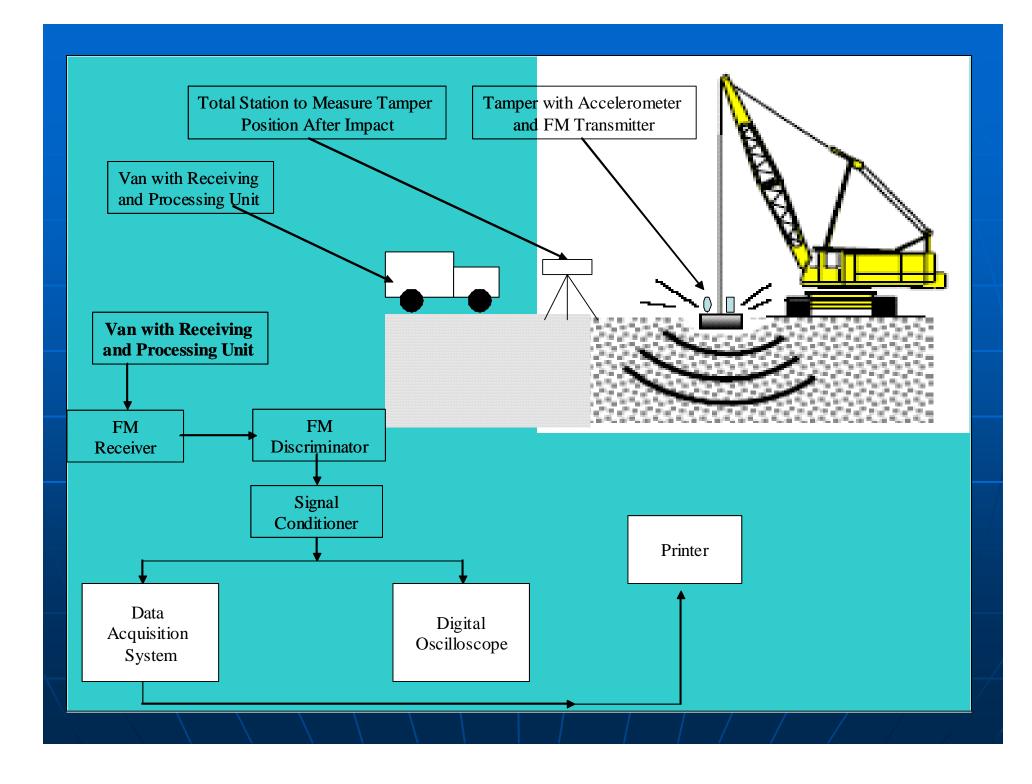
British Standard 7385: Part 2-1993, lays down following safety limits for various structures having different natural frequencies: >Reinforced or framed structures industrial and heavy commercial buildings at 4 Hz and above 50 mm/s >Un-reinforced or light framed structures residential or light commercial type buildings at 4 Hz –15 Hz 15-20 mm/s >Un-reinforced or light framed residential or light commercial type buildings at 15 Hz –40 Hz and above 20-50 mm/s

Effect on Humans

>0.1 mm/sec >0.15 mm/sec >0.35 mm/sec >1.00 mm/sec >2.00 mm/sec >6.00 mm/sec >14.00 mm/sec >17.8 mm/sec

not noticeable nearly not noticeable seldom noticeable always noticeable clearly noticeable strongly noticeable very strongly noticeable severe noticeable

MONITORING AND CONTROL



DESIGN AND ANALYSIS CONSIDERATIONS

- Depth of improvement, d
- Impact energy, E
- Influence of cable drag
- > Equipment limitations
- Influence of tamper size
- Grid spacing, S
- Time delay between passes
- Soil conditions

Depth of Improvement

Primary concern > Depends on: Soil conditions Energy per drop
 Contact pressure of tamper Grid spacing Number of passes Time lag between passes

Impact Energy, E

Weight of tamper times the height of drop
Main parameter in determining the depth of improvement

Can be calculated from the equation

 $D_{max} = n \sqrt{W \times H}$

(Free falling of weights)

Influence of Cable Drag

Cable attached to the tamper causes friction and reduces velocity of tamper

Free fall of tamper is more efficient

Equipment limitations

Crane capacity
Height of drop
Mass of tamper
Tamper size

Grid Spacing

Significant effect on depth of improvement

- First pass compacts deepest layer, should be equal to the compressible layer
- Subsequent passes compact shallower layers, may require lesser energy

Ironing pass compacts top layer

Time Delay between Passes

> Allow pore pressures to dissipate

Piezometers can be installed to monitor dissipation of pore pressures following each pass

