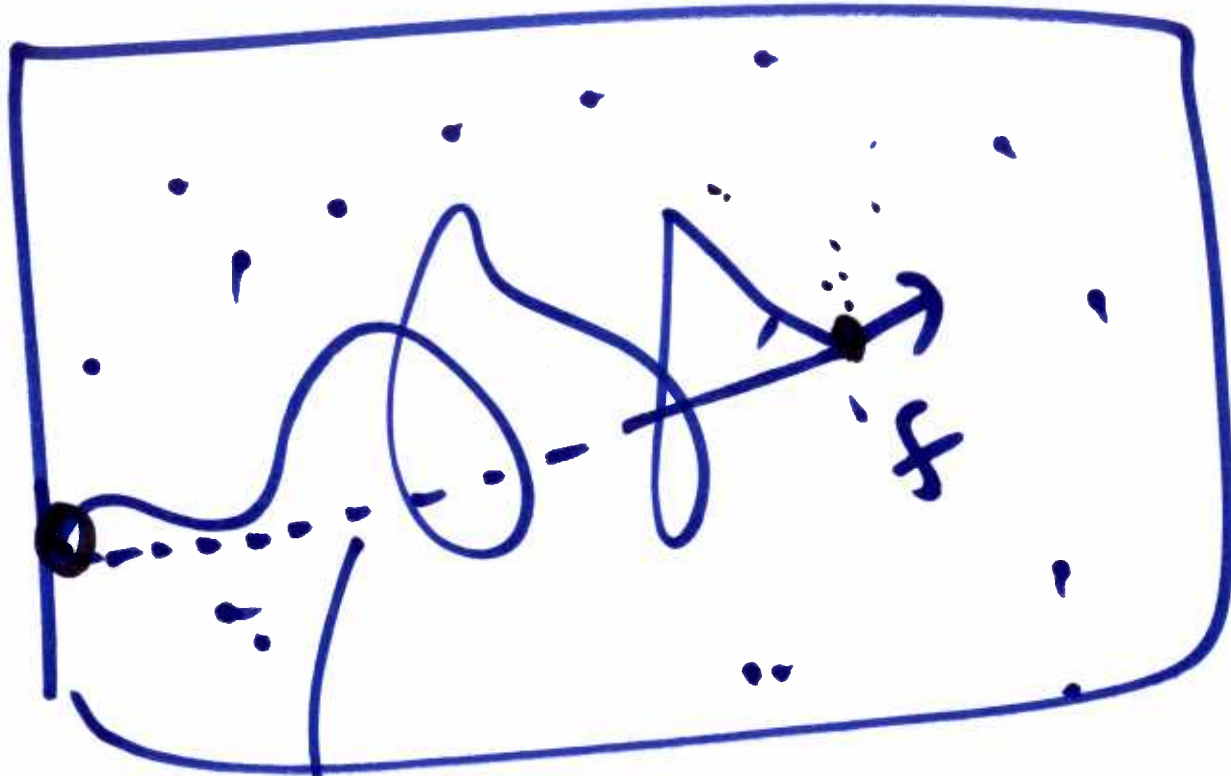
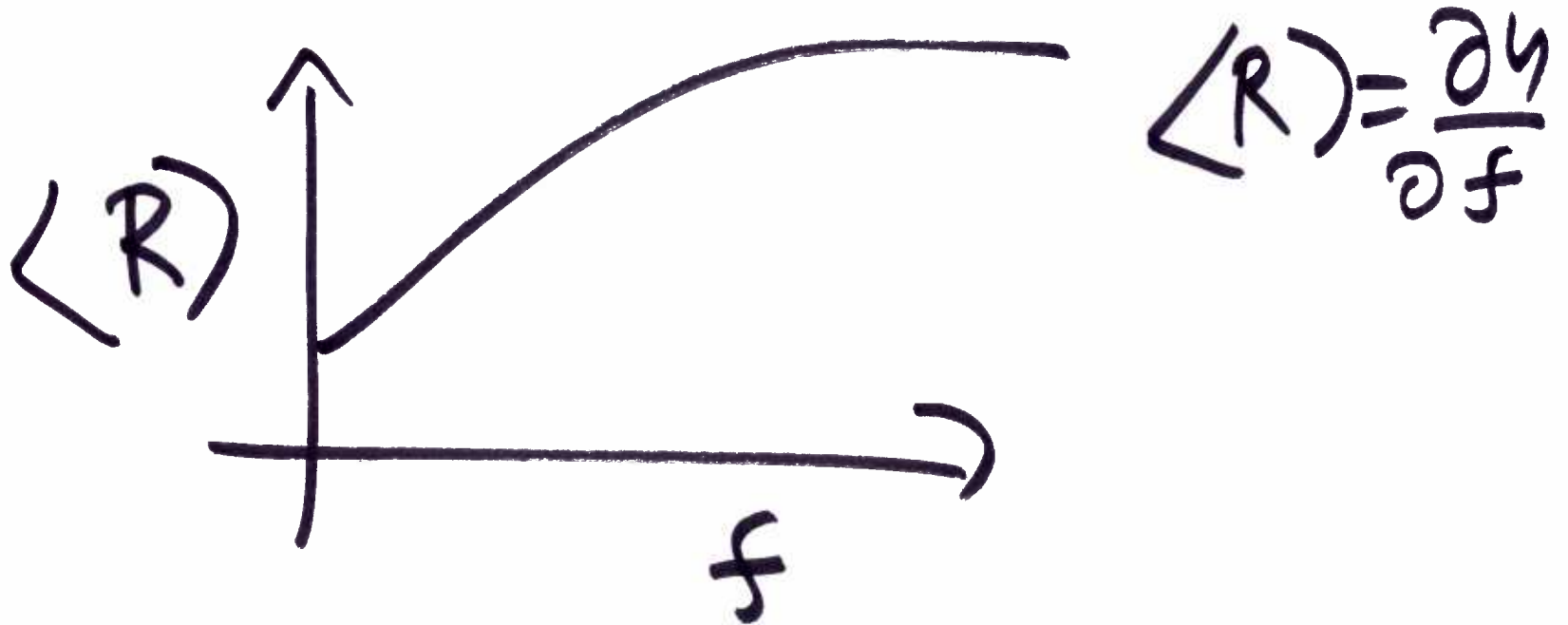


Prof. Ranjith
Date: - 17/05/2012
Lec. 37



$$\langle R \rangle = \frac{\partial G}{\partial f}$$

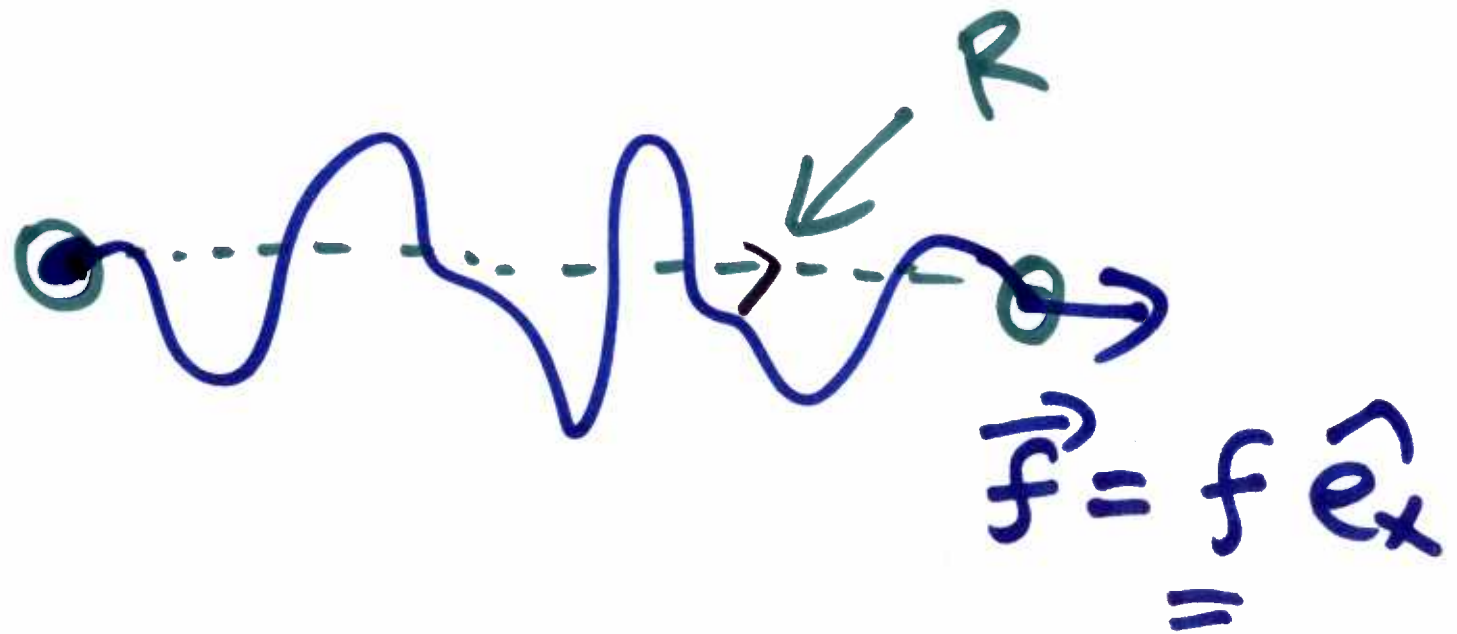
Force - Extension Relation



$$\psi(f) = ? = -k_B T \ln \underline{Z}$$

Free energy $G(f)$

for single-stranded DNA



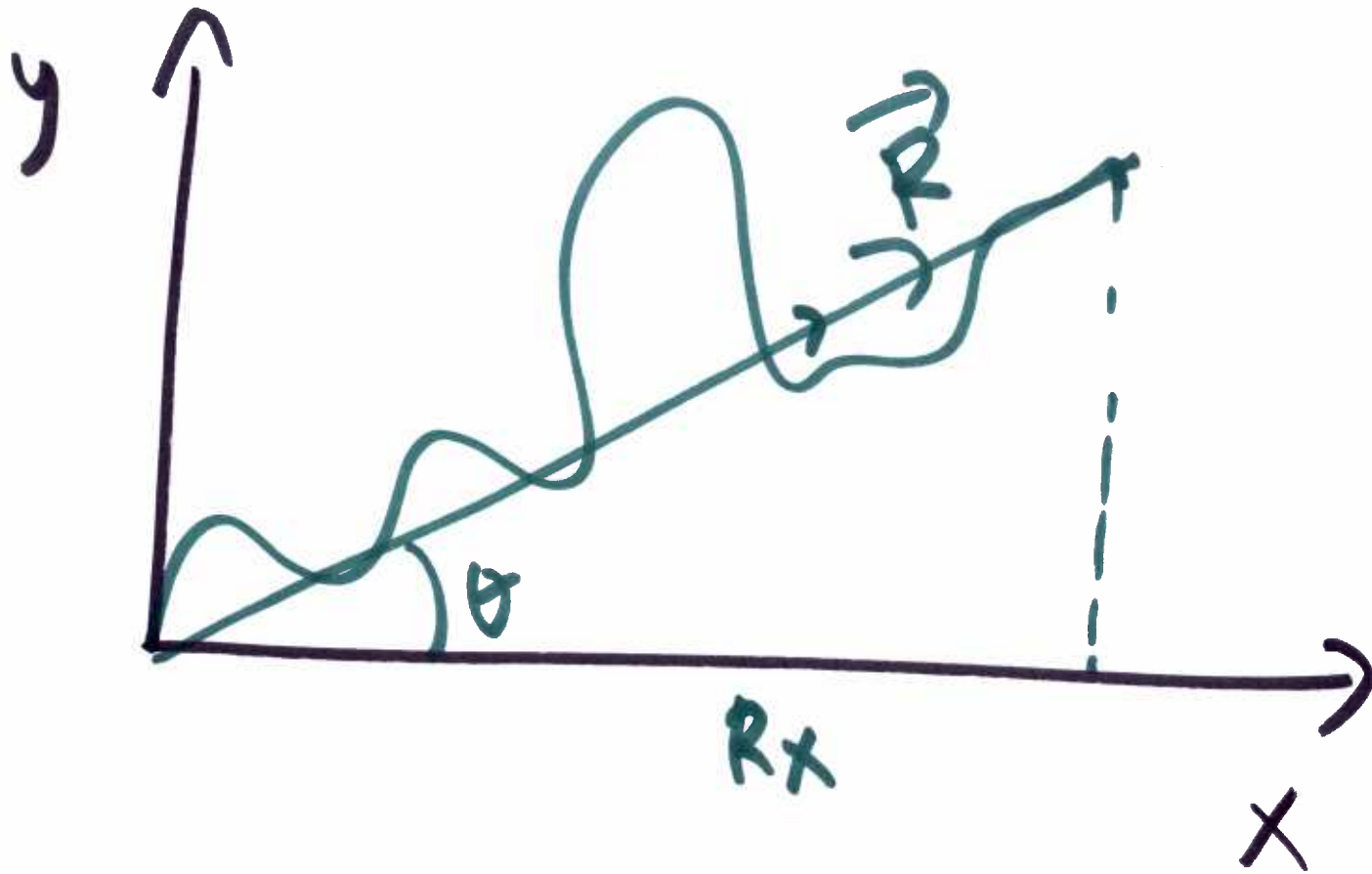
$$F_D = A \sum_i (1 - \hat{t}_i \cdot \hat{t}_{i+1})$$

$$F_D^s \approx 0$$

$$E = f \cdot \vec{R}$$

$$= f e_x \cdot (R_x \hat{e}_x + R_y \hat{e}_y + R_z \hat{e}_z)$$

$$E = f R_x$$



$$E = f R_x \quad \approx = \tilde{f} \cos \theta$$

$$F_B = 0$$

$$F_P = f \cos \theta$$

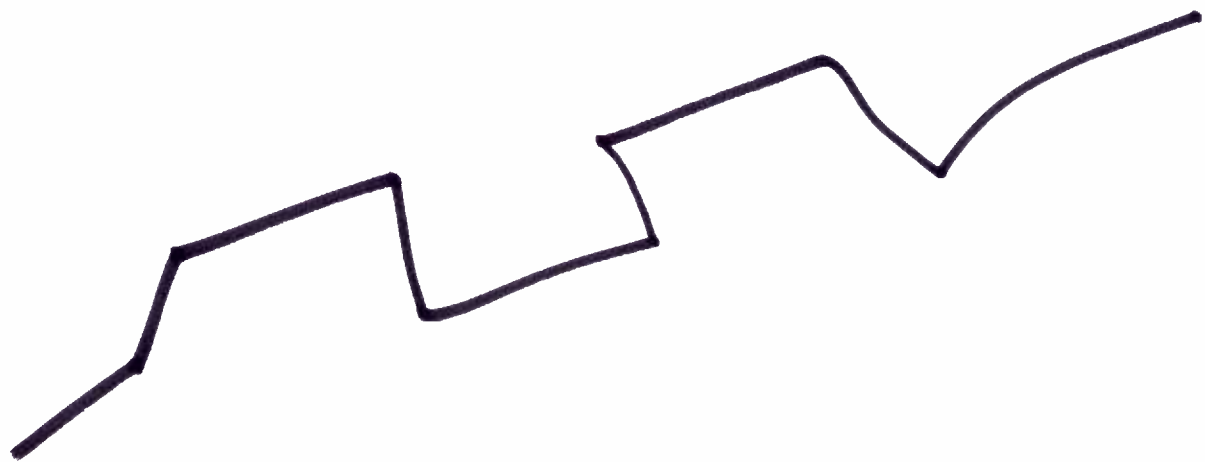
$$F = f \cos \theta$$

$$\begin{aligned} Z &= \sum_i e^{-\beta E_i} \\ &= \int \{\text{states}\} e^{-\beta E} \\ &= \int \rho(\theta) e^{-\beta \tilde{f}(\theta)} \end{aligned}$$

$$\int \underline{d\vec{t}} = \int_{-1}^1 d(\cos\theta) \int_0^{2\pi} d\varphi$$

$$\int_0^{2\pi} d\varphi \int_{-1}^1 d(\cos\theta) e^{-\beta f^2 \cos\theta}$$

$$Z = \left[4\pi \sinh \frac{\beta \tilde{f}}{\beta \tilde{f}} \right]^N$$




$$G = -k_B T \ln Z$$

$$= N \left[\ln \frac{f^2}{k_B T} - \ln \sinh \frac{f^2}{k_B T} \right]$$

$$G(f) = N \left[\ln \frac{fb}{k_B T} - \ln \sinh \frac{fb}{k_B T} \right]$$

$$\langle R_x \rangle = \frac{\partial G}{\partial f}$$

$$\langle R_x \rangle = Nb \left[\frac{1}{\tanh \frac{fb}{k_B T}} - \frac{k_B T}{fb} \right]$$


flexible polymer

$$\langle R_x \rangle = \frac{1}{\tanh(x)} - \frac{1}{x}$$

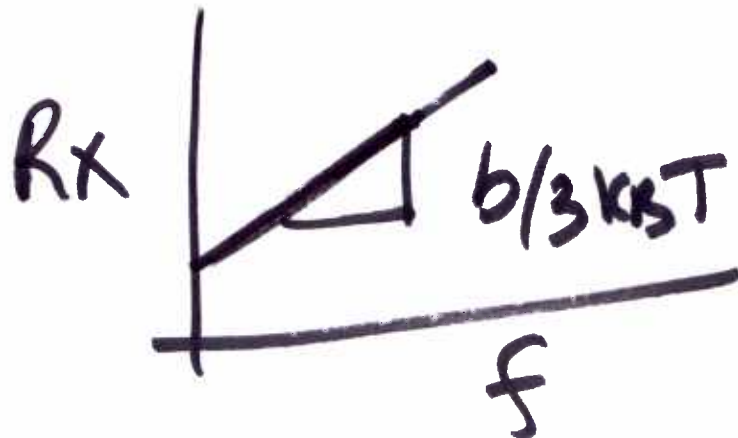
$$x \ll 1 \Rightarrow f \ll \frac{k_B T}{b}$$

$$\langle R_x \rangle \approx \cancel{x} \frac{x}{3} + \dots O(x^3)$$

For small force


$$f \ll \frac{k_B T}{b}$$

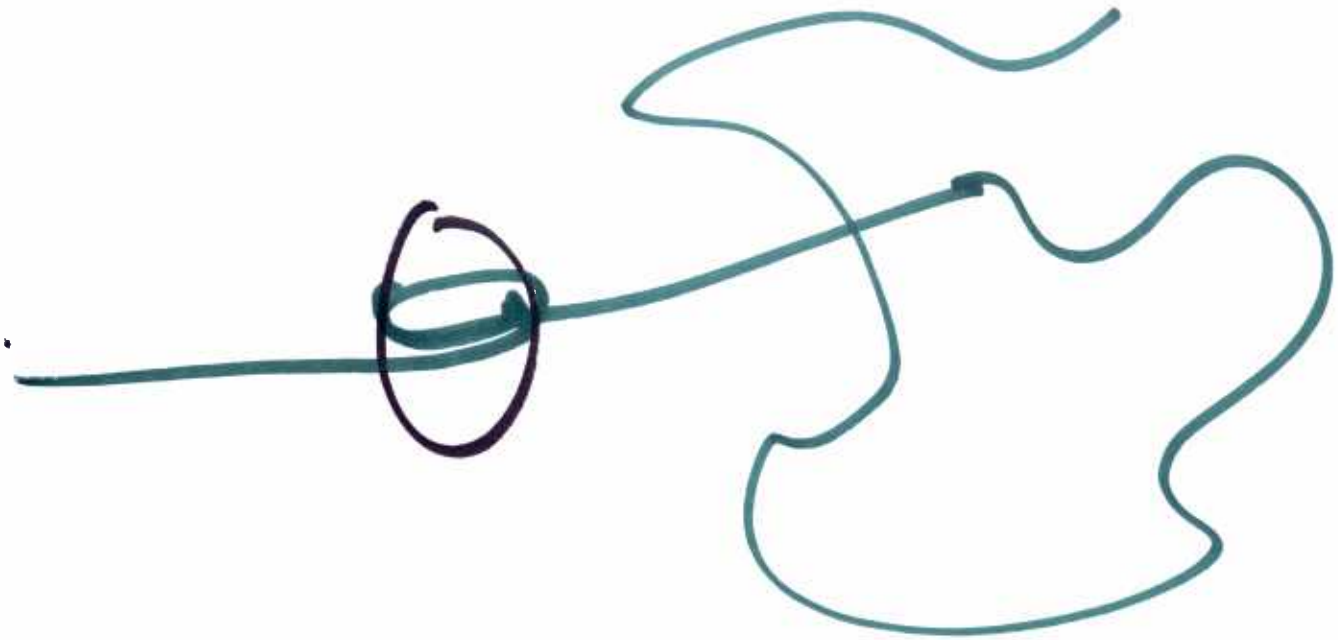
$$\langle R_x \rangle = \frac{x}{3} + \dots = \frac{fb}{3k_B T}$$



for large f

$$f \gg \frac{k_B T}{b}$$


$$\frac{\langle R_x \rangle}{\Delta b} = N_b \left[1 - \frac{k_B T}{f b} \right]$$



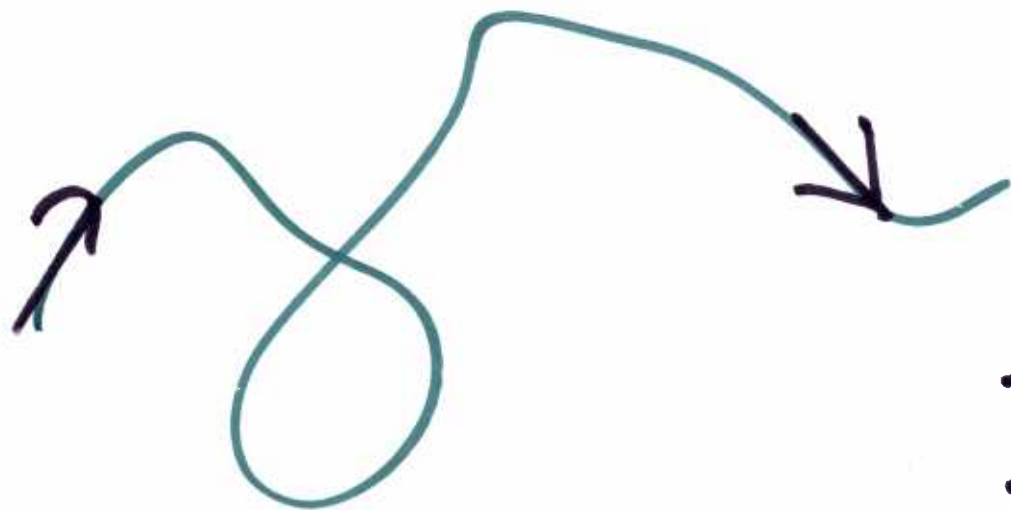
$$E = \int \textcircled{K} \left(\frac{\partial t}{\partial s} \right)^2 ds$$

$$\int \textcircled{K} \left(\frac{\partial^2 r}{\partial s^2} \right)^2 ds$$

$$E = \textcircled{A} \sum_i (1 - \vec{E}_i \cdot \vec{E}_{i+1})$$

Persistence length





$$\vec{t}_i \cdot \vec{t}_{i+r}$$

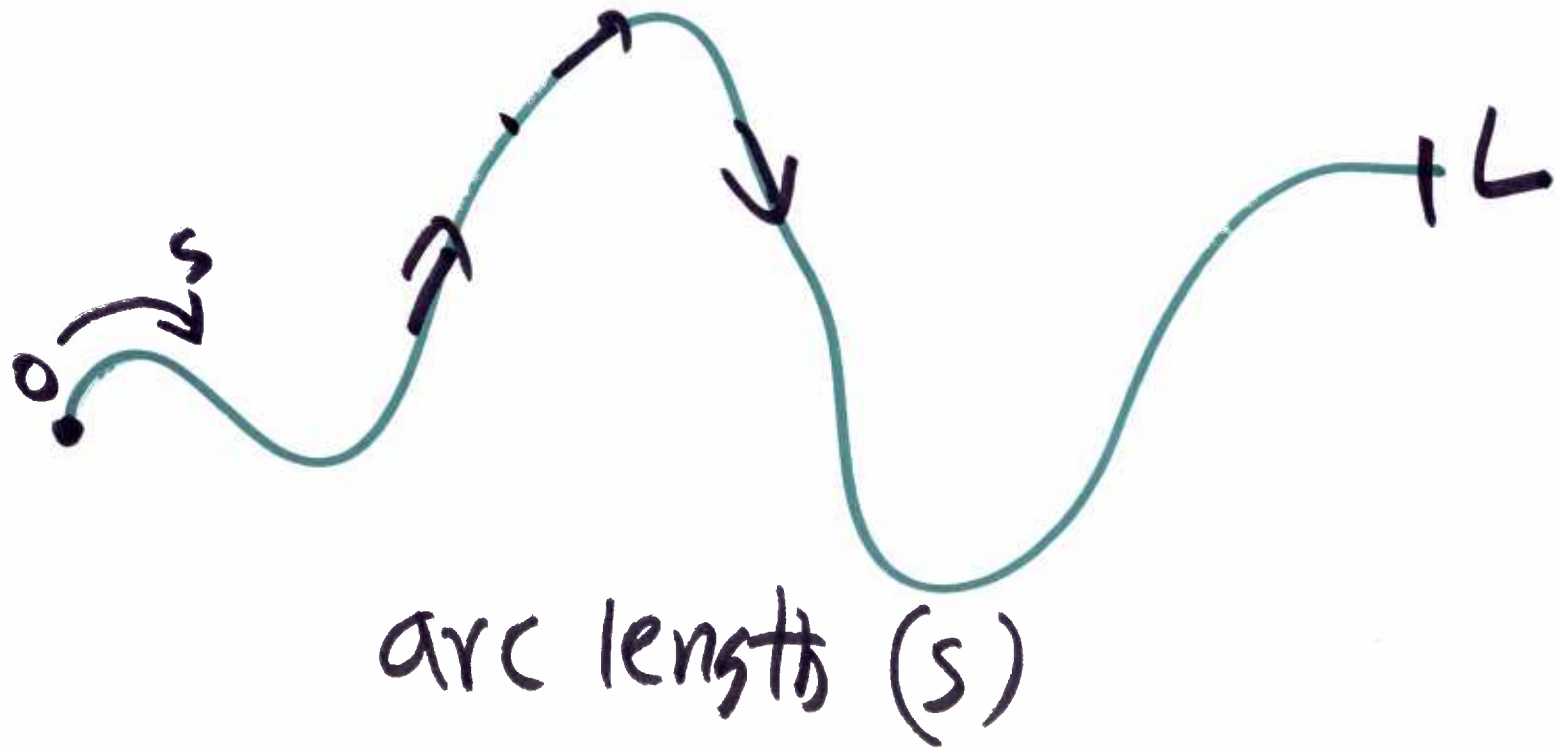




$$\vec{t}_i \cdot \vec{t}_{i+r} = (1) \cos \theta$$
$$= 1$$

$$|\vec{t}_i| = 1$$

$$\langle \hat{t}(s) \cdot \hat{t}(s+ds) \rangle = e^{-\frac{ds}{Lp}}$$



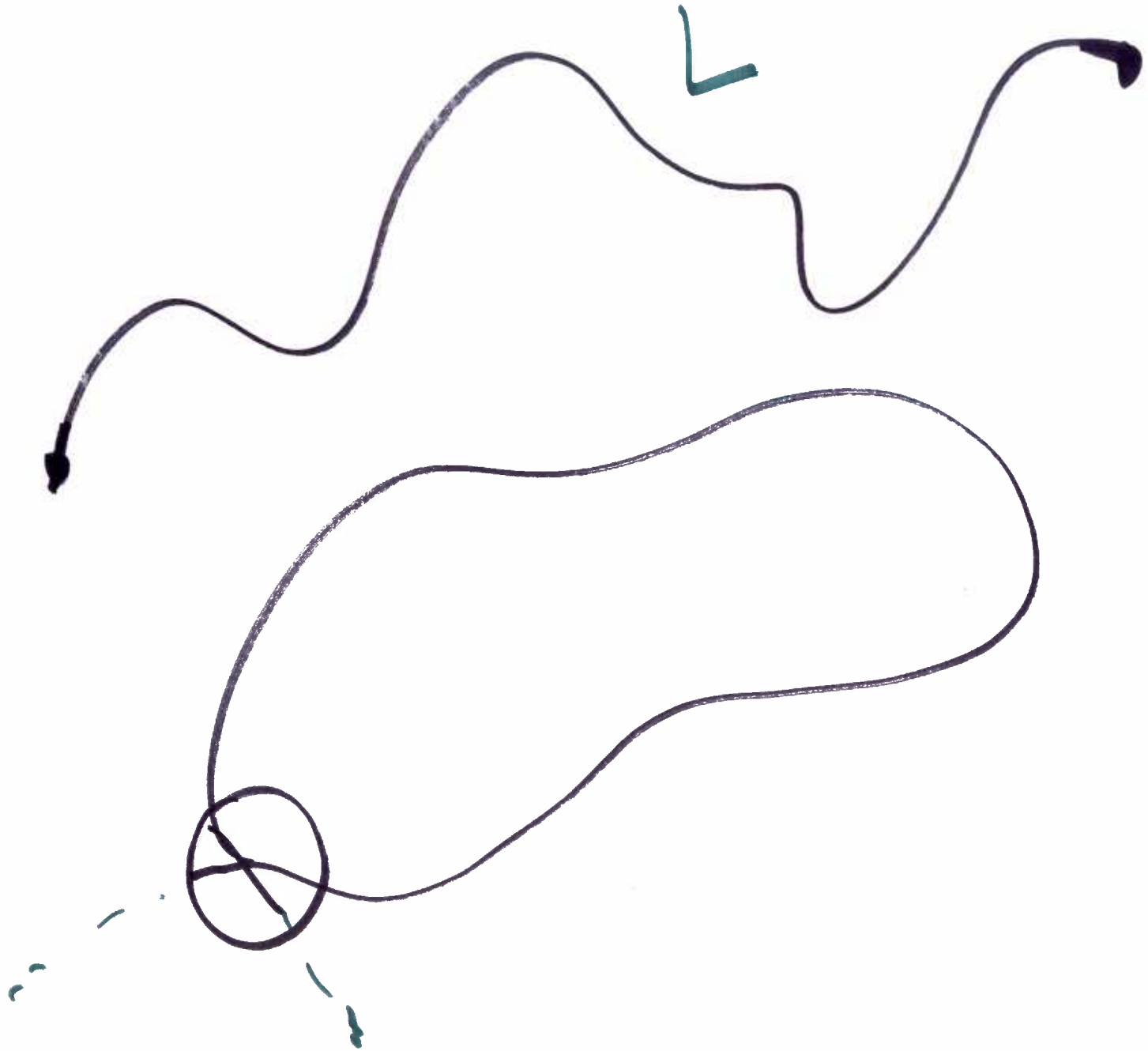
$L_p =$ Persistence length

$$L_p = \frac{K}{k_B T} = \frac{\text{Bending stiffness}}{k_B T}$$

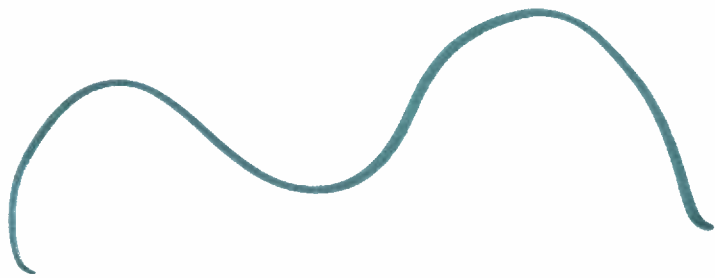
L_p for DNA = 50 nm \approx 150 bp

L_p for actin \approx 10 μ m

L_p for Microtubule \approx mm



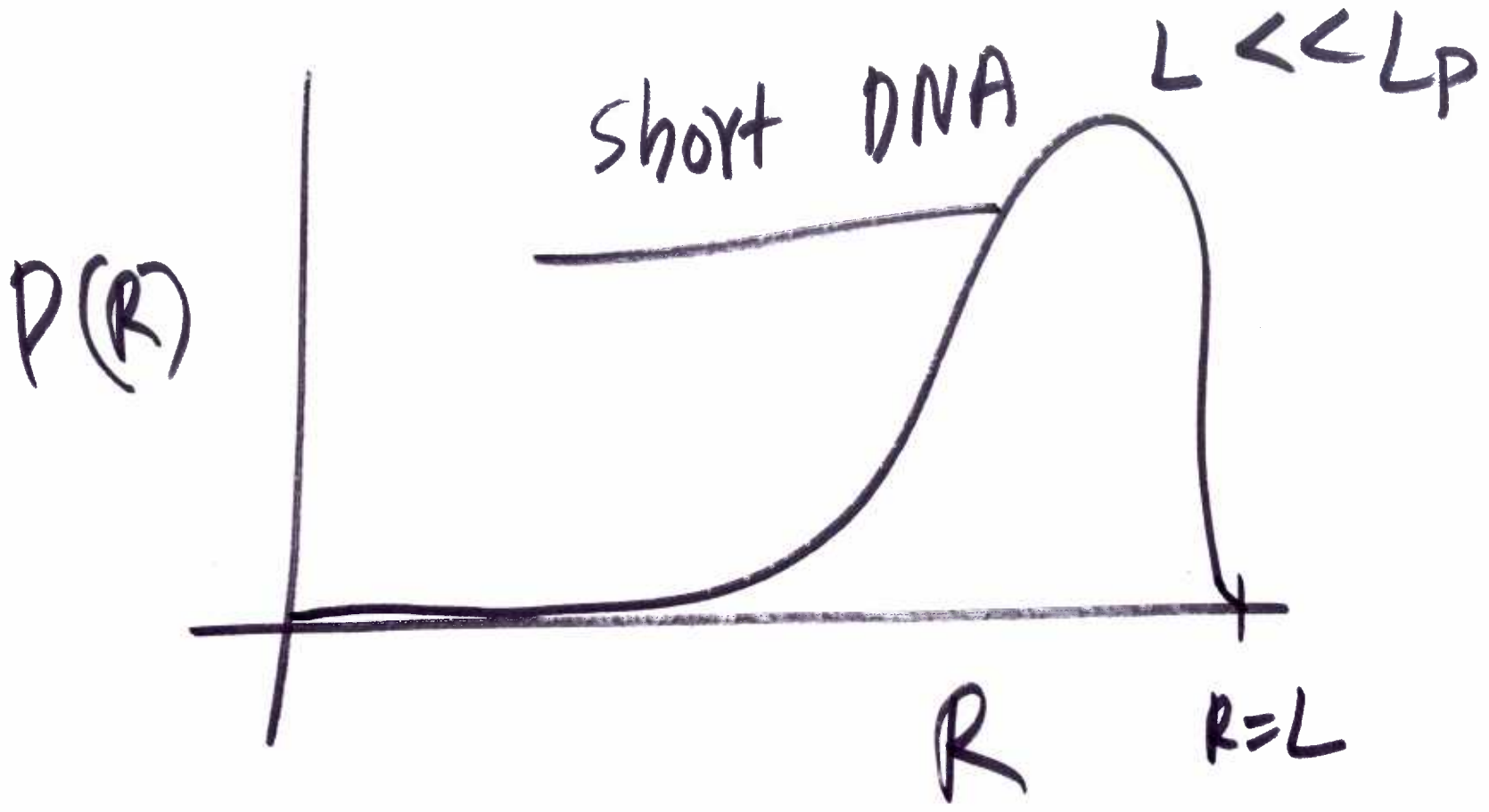
$$Z = \int e^{-\beta E} \{dt\}$$



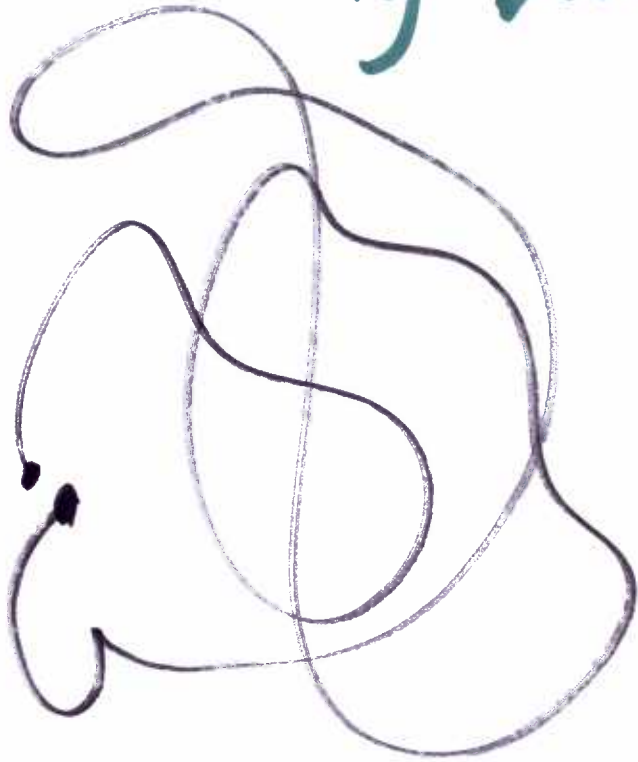
$$P = \frac{e^{-\beta E}}{Z}$$

$$= \frac{e^{-\beta E (R=0)}}{Z}$$

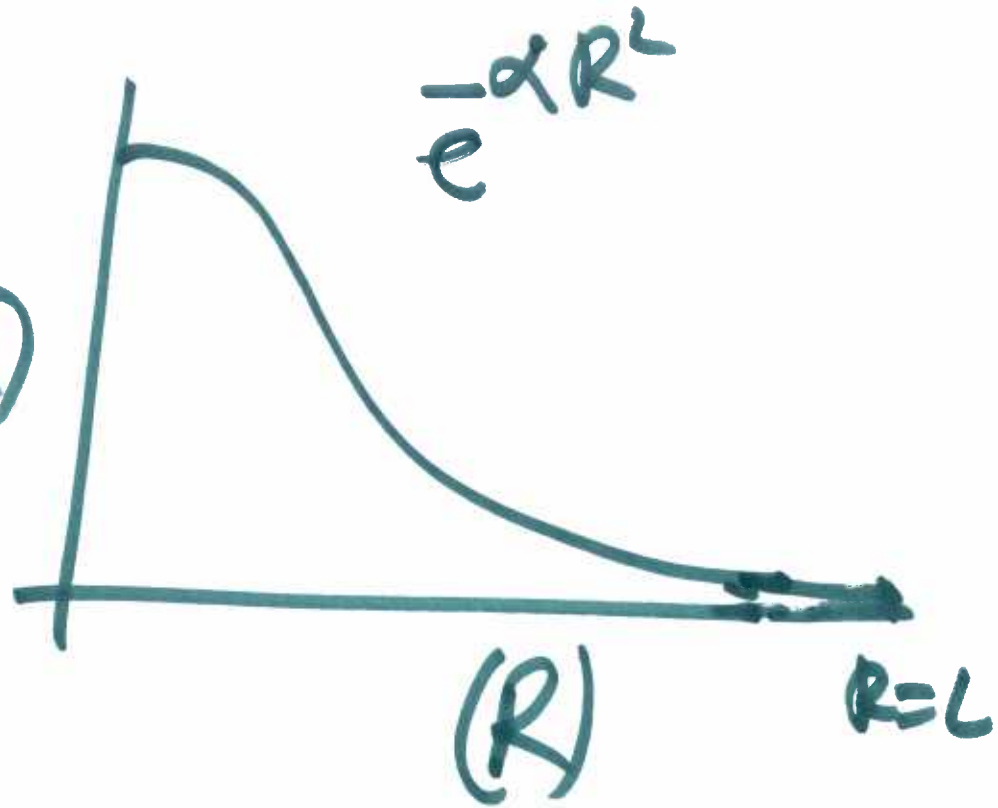
$P(R)$ = Probability that DNA
will have end-to-end
distance = R



Long DNA

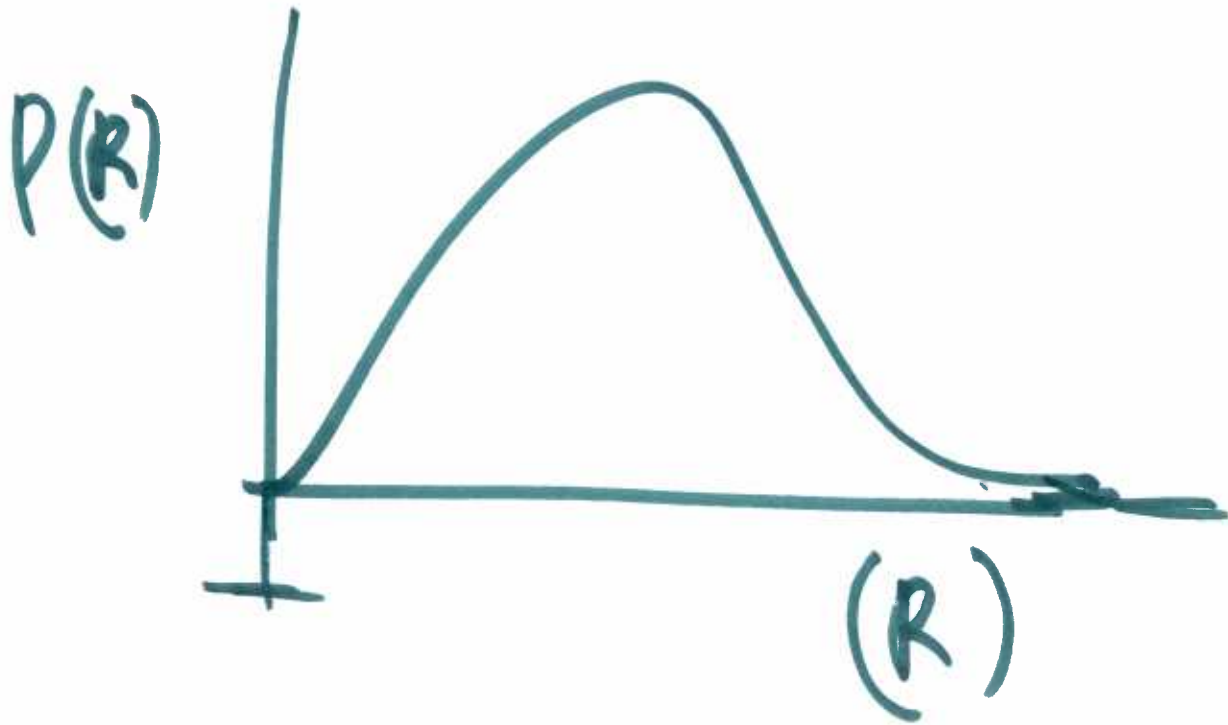


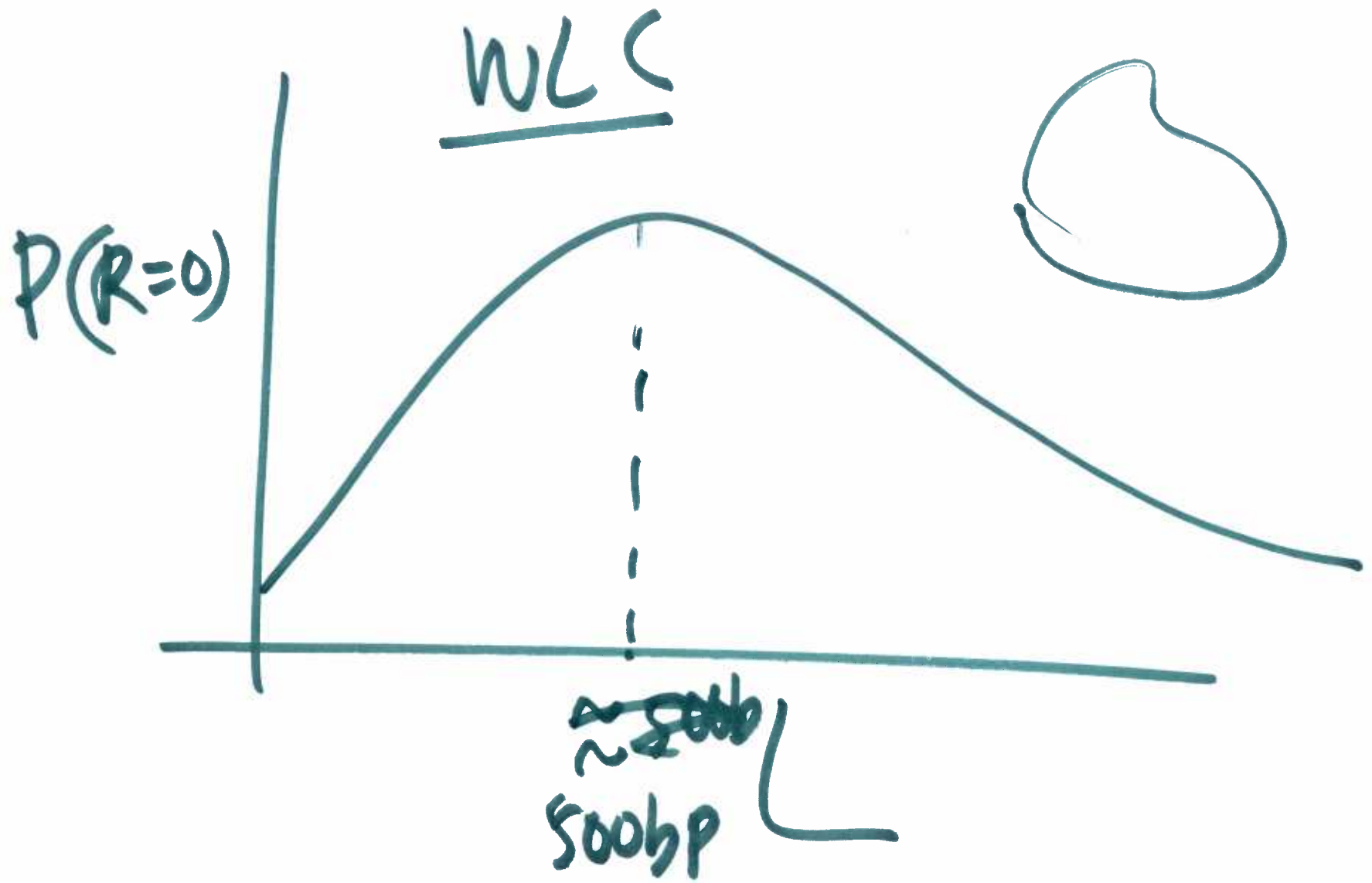
$P(R)$



$L \gg \lambda_p$

$$L \sim L_P$$





$$G = H - TS$$

$$F = E - TS$$