

$$\frac{-\partial}{\partial a} \sqrt{\pi/a} = \sqrt{\pi} \left(\frac{-\partial}{\partial a} a^{-1/2} \right)$$

$$\int_{-\infty}^{\infty} x^2 e^{-ax^2} dx = \frac{\sqrt{\pi}}{2} a^{-3/2}$$

$$\int_{-\infty}^{\infty} \frac{x^2 e^{-ax^2}}{dx}$$

$$\frac{-\frac{\partial}{\partial a} e^{-ax^2}}{\partial a} = \frac{-x^2 e^{-ax^2}}{x^2 e^{-ax^2}}$$

$$\int_{-\infty}^{\infty} \frac{\partial}{\partial a} e^{-ax^2} dx = \frac{\partial}{\partial a} \int_{-\infty}^{\infty} dx e^{-ax^2}$$

!

$$\int_{-\infty}^{\infty} e^{-ax^2} dx = \sqrt{\frac{\pi}{a}}$$

$$\int x e^{-ax^2} dx = \left(\frac{x}{-2a} \right)$$

$$\int x^2 e^{-ax^2} dx = \left(\frac{x^2}{-2a} \right)$$

$$I^2 = \frac{\pi}{a} \Rightarrow I = \sqrt{\pi/a}$$

$$\pi \left[0 \quad -\frac{1}{a} \right]$$

↑

$$\pi \int_0^{\infty} e^{-at} dt$$

$$\pi \left[\frac{e^{-at}}{-a} \right]_0^{\infty}$$

$$\pi \left[\frac{-e^{-a\infty}}{a} - \frac{-e^{-a0}}{-a} \right]$$

$$2\pi \int_0^{\infty} dr \, r e^{-ar^2}$$

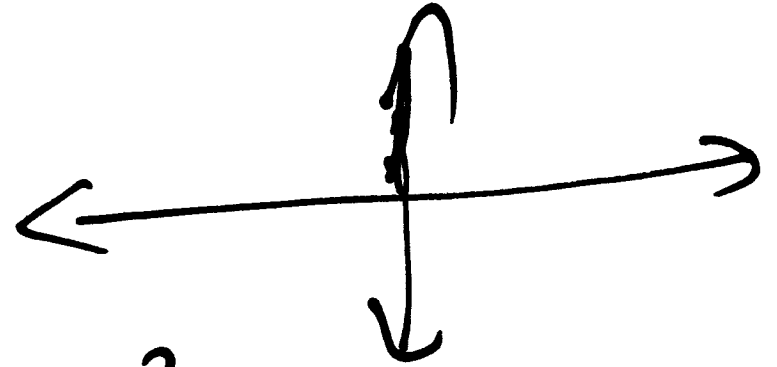
$$r^2 = t$$

$$2r dr = dt$$

$$r dr = \frac{dt}{2}$$

$$2\pi \int_0^{\infty} \frac{dt}{2} e^{-ta}$$

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} dx dy e^{-ar^2}$$

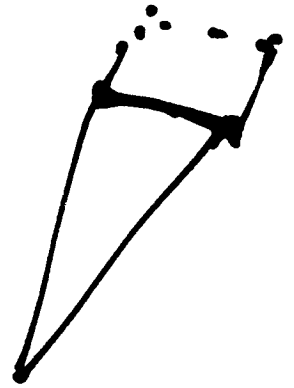


$$\int \int r d\theta dr \Rightarrow e^{-ar^2}$$
$$\int_0^{2\pi} d\theta \int_0^{\infty} dr r e^{-ar^2}$$

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$e^{-a(x^2+y^2)} = e^{-ar^2}$$



$$\int \int \underline{dx dy} \rightarrow r dr d\theta$$

$$I = \int_{-\infty}^{\infty} dx e^{-ax^2}$$

$$I = \int_{-\infty}^{\infty} dy e^{-ay^2}$$

$$I^2 = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy e^{-ax^2} \cdot e^{-ay^2}$$

use plane-polar coordinates

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \underline{dx dy} e^{-a(x^2+y^2)}$$

$$I^2 = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy e^{-a(x^2+y^2)}$$

Integral of e^{-ax^2}

$$\int_{-\infty}^{\infty} e^{-ax^2} dx = ?$$

$$J = D \frac{\partial C}{\partial x} \uparrow$$

$$= -D \frac{\partial}{\partial x} 10x^2 = -D 20x \\ = -20Dx \uparrow$$

$$\frac{\partial C}{\partial k}: D \frac{\partial^2 C}{\partial x^2} = -20D$$

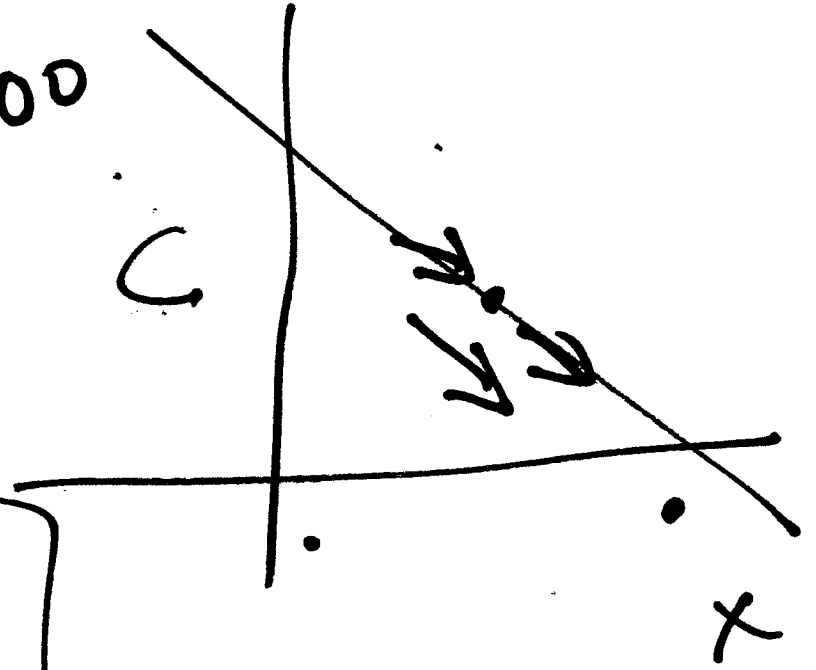
$$\frac{\partial C}{\partial t} = D \frac{\partial^2 C}{\partial x^2} \quad | \quad J = 10D$$

$$= \frac{\partial J}{\partial x}$$

$$= \frac{\partial 10D}{\partial x} = 0$$

$$\frac{\partial C}{\partial t} = 0 \Rightarrow C: \text{a const.}$$

$$C = -10x + 100$$



$$J = 10x + C$$

$$= 0 \left[\frac{\partial 10x}{\partial x} + \frac{\partial C}{\partial x} \right]$$



$$\vec{J} = -D \frac{\partial C}{\partial x} \hat{x}$$

$$C = -10x + 100$$

$$-D \frac{\partial C}{\partial x} = D \frac{\partial}{\partial x} [-10x + 100]$$

$$D = \frac{4 (10^{-2})^2}{2 \times 3600} = \frac{4 \times 10^{-4}}{7.2 \times 10^3}$$

$$\approx \frac{1}{2} 10^{-7} \frac{\text{m}^2}{\text{s}}$$

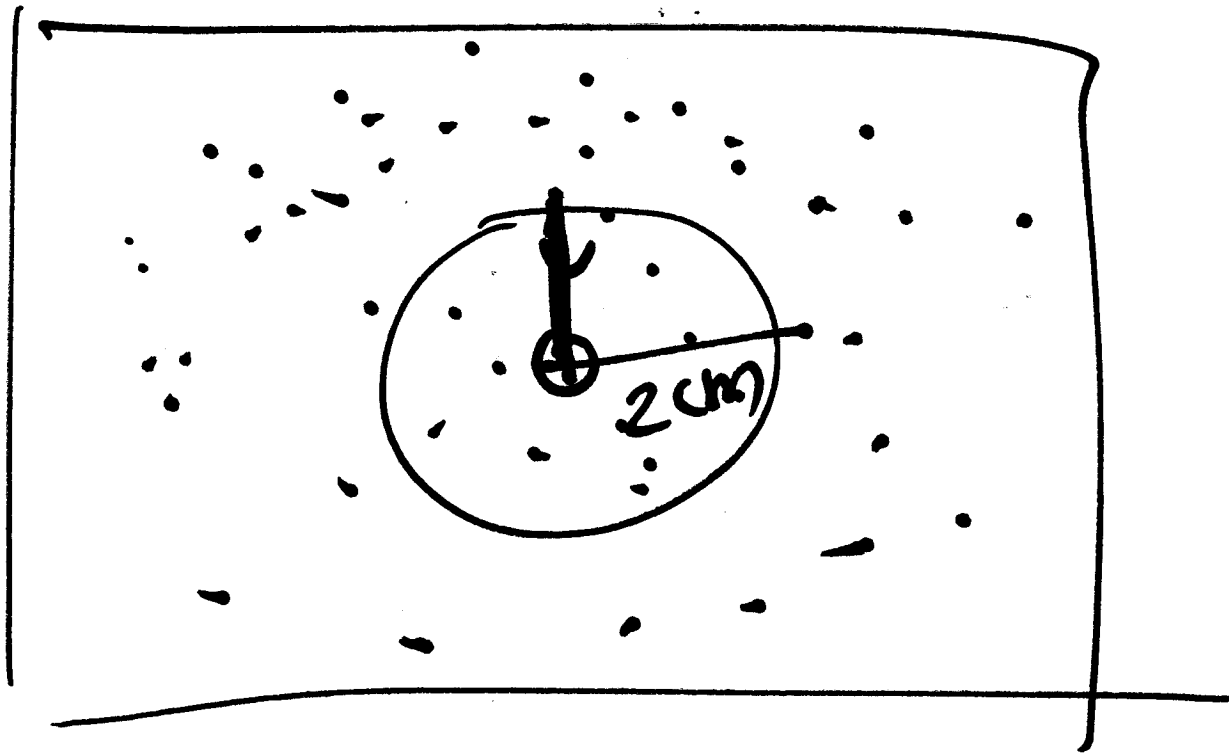


$$\langle r^2 \rangle = \frac{2Dt}{1}$$

$$t = 1 \text{ hour} = 60 \text{ min} \\ = 3600 \text{ s}$$

$$\langle r^2 \rangle = 4 \text{ cm}^2$$

$$4(10^{-2})^2 \text{ m}^2 = 20 \text{ 3600 s}$$



22 1 hour

$$\lambda = \frac{k_B T}{D}$$

$$(T \approx 10^2 \text{ K})$$

$$(k_B \approx 10^{-23} \text{ C})$$

$$\approx \frac{10^{-21} \text{ J}}{D}$$

$$\lambda \approx \frac{10^{-21} \text{ J}}{10^{-12} \text{ cm}^2/\text{s}} \approx 10^{-9} \frac{\text{J}}{\text{cm}^2 \text{ s}}$$

$$D = 10^{-12} \frac{(3 \times 10^7 \text{ bp})^2}{\text{s}}$$

$$= 10^{-12} \times 9 \times 10^{14} \frac{\text{bp}^2}{\text{s}}$$

$$= 9 \times 10^2 \frac{\text{bp}^2}{\text{s}} = 900 \frac{\text{bp}^2}{\text{s}}$$

$$D = 10^{-12} \frac{\text{cm}^2}{\text{s}}$$

$$3\text{bp} = 1\text{nm} = 10^{-9}\text{m}$$

$$3\text{bp} = 10^{-7}\text{cm}$$

$$1\text{cm} = \frac{3}{10^{-7}}\text{bp} = 3 \times 10^7\text{bp}$$



$$D = 10^{-12} \frac{\text{cm}^2}{\text{s}}$$

$$D = \frac{k_B T}{6\pi\eta a} = \frac{k_B T}{\xi}$$

$$\vec{f}_2 = \cancel{g(x)}$$

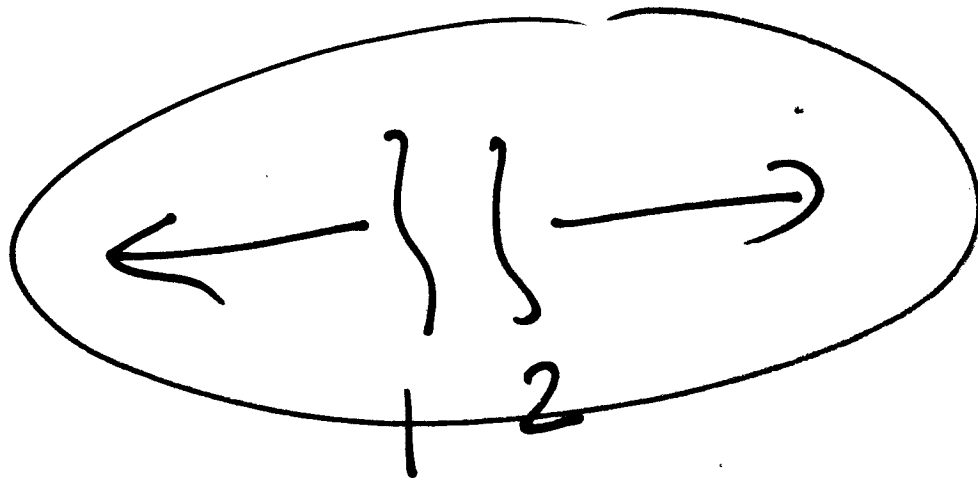
$$\vec{f}_2 = g(x, t) \hat{x}$$

$$\vec{f}_1 = -p(x, t) \hat{x}$$

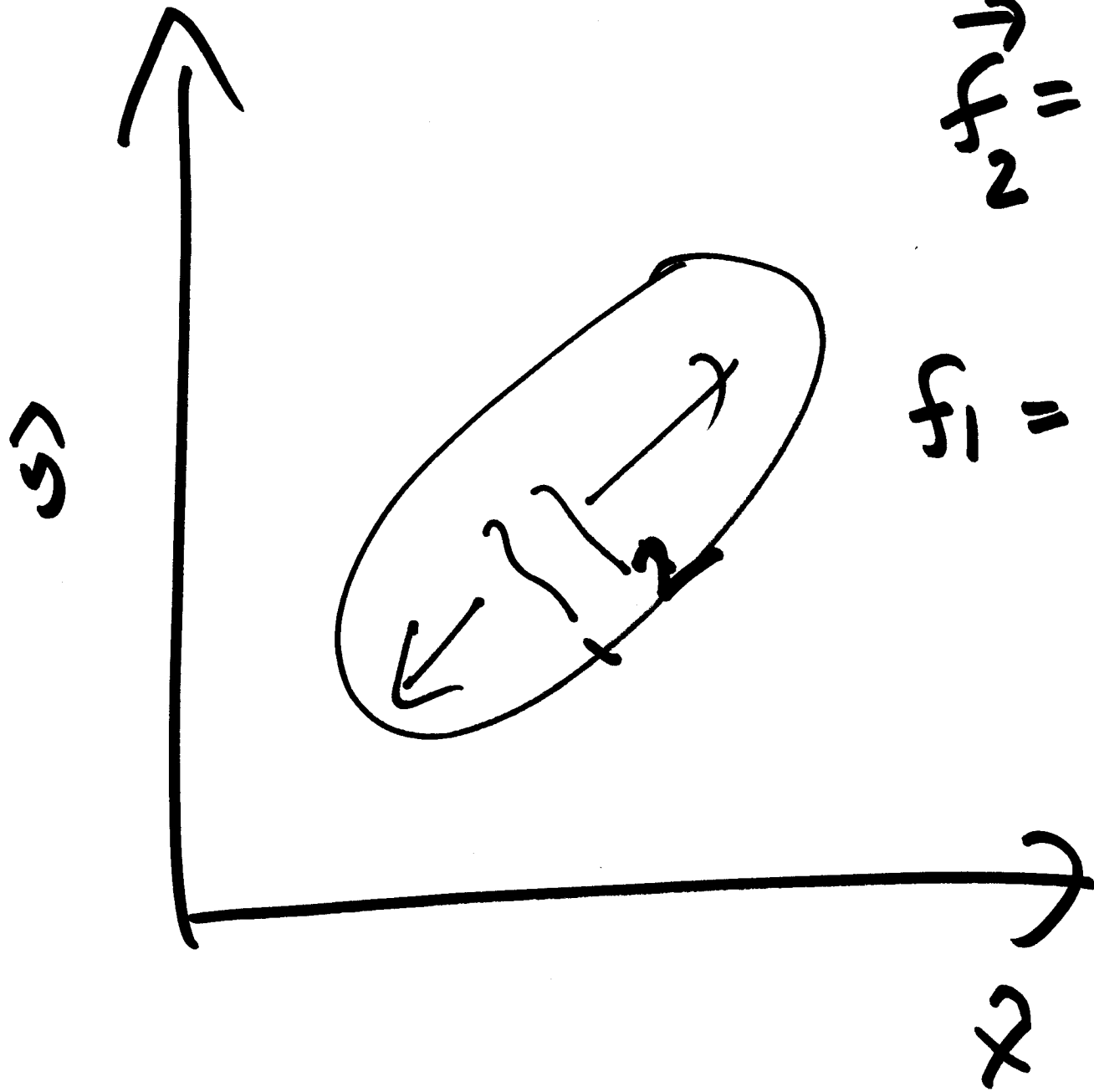
$$\vec{f}_1 = f_0(t) \hat{x}$$

$$\vec{f}_2 = -f_0(t) \hat{x}$$

~~$$\vec{f}_1 = g(x) \hat{x}$$~~



$$\begin{aligned} \vec{f}_2 &= f_0 \hat{x} \\ \vec{f}_1 &= -f_0 \hat{x} \end{aligned}$$



$$\vec{f}_2 = g_1 \hat{x} + g_2 \hat{y}$$

$$f_1 = ()^{\hat{x}} - f_2$$